Fair Multiple Decision Making Through Soft Interventions (Supplementary File)

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1 **Proof of Theorem 1**

Theorem 1. For any classification-calibrated loss function ϕ satisfying $\phi(0) = 1$ and $\inf_{\alpha \in \mathbb{R}} \phi(\alpha) = 0$, any measurable function h_k for predicting Y_k , we have

$$\psi(R(h_k) - R^*) \le R_\phi(h_k) - R_\phi^*,$$

where $\psi(\delta)$ is a non-decreasing function mapping from [0, 1] to $[0, \infty)$.

Lemma 1. For ψ , H_{ϕ} and H_{ϕ}^{-} , they have following properties.

- 1. For $\lambda \in [0, 1]$ and $\gamma \in \mathbb{R}$, $\psi(\lambda \gamma) \leq \lambda \psi(\gamma)$.
- 2. $H_{\phi}^{-}(\eta) \ge H_{\phi}(\eta)$ for $\eta \in [0, 1]$.
- 3. $\eta \leq H_{\phi}(\eta)$ for $\eta \in [0, 1/2]$.
- 4. $\eta \leq 1 \leq H_{\phi}^{-}(\eta)$ for $\eta \in [0, 1]$.

Proof. Parts 1,2,3 are proved in [1]. For Part 4, note that H_{ϕ} is concave and symmetric about 1/2, meaning that it gets its minimum at $\eta = 0, 1$ and maximum at $\eta = 1/2$ [1]. We have $H_{\phi}(0) = H_{\phi}(1) = \inf_{\alpha \in \mathbb{R}} \phi(\alpha) = 0$. Meanwhile, we have $H_{\phi}(1/2) = 1/2 \cdot \inf_{\alpha \in \mathbb{R}} (\phi(\alpha) + \phi(-\alpha))$. Due to the convexity and symmetry between $\phi(\alpha)$ and $\phi(-\alpha)$, we can see that $H_{\phi}(1/2) = \phi(0) = 1$. Then, since H_{ϕ} is concave, we have $\eta H_{\phi}(1/2) + \overline{\eta} H_{\phi}(0) \leq H_{\phi}(\eta/2 + \overline{\eta} \cdot 0)$, which leads to $\eta \leq H_{\phi}(\eta/2) \leq H_{\phi}(\eta)$ for $\eta \in [0, 1/2]$.

For Part 5, note that H_{ϕ}^- is concave on [0, 1/2] and on [1/2, 1] and also symmetric about 1/2 [1]. Since $H_{\phi}^-(1/2) = H_{\phi}(1/2) = 1$ and $H_{\phi}^-(0) = H_{\phi}^-(1) = \inf_{\alpha \leq 0} \phi(\alpha) = \phi(0) = 1$, we have $H_{\phi}^-(\eta) \geq 1 \geq \eta$.

Next, we first prove Theorem 1 based on the toy example in the main paper, and then explain how this proof can be extended to general situations.

1.1 Proof of Theorem 1 Based on Toy Example

Proof of Theorem 1. The causal graph of the toy example is shown in Fig. 1. In the example, we have two classifiers h_1, h_2 . Note that $R_{\phi}(h_1)$ is the same as that of a single decision model, so we

34th Conference on Neural Information Processing Systems (NeurIPS 2020), Vancouver, Canada.

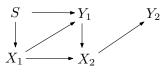


Figure 1: The toy model.

focus on $R_{\phi}(h_2)$. Denoting $\mathbf{Z} = \{S, X_1, X_2\}$, we define

$$c_1(\mathbf{z}) = \frac{P(y_1^+|s, x_1, x_2)}{P(y_1^+|s, x_1)} + \frac{P(y_1^-|s, x_1, x_2)}{P(y_1^-|s, x_1)},$$

and define

$$\eta_1(\mathbf{z}) = \frac{P(y_1^-|s, x_1, x_2)}{c_1(\mathbf{z})}, \quad \eta_2(\mathbf{z}) = P(y_2^+|x_2),$$

and

$$\bar{\eta}_1(\mathbf{z}) = 1 - \eta_1(\mathbf{z}), \quad \bar{\eta}_2(\mathbf{z}) = 1 - \eta_2(\mathbf{z}),$$

For simplifying representation, in the remaining of this file we omit (z) in all expressions. Note that

$$\begin{split} R_{\phi}(h_{2}) &= \mathop{\mathbb{E}}_{\mathbf{z}} \left[c_{1} \left(\eta_{1} \eta_{2} \phi(h_{1}(x_{1})) \phi(h_{2}(x_{2})) + \bar{\eta}_{1} \eta_{2} \phi(-h_{1}(x_{1})) \phi(h_{2}(x_{2})) \right. \\ &+ \eta_{1} \bar{\eta}_{2} \phi(h_{1}(x_{1})) \phi(-h_{2}(x_{2})) + \bar{\eta}_{1} \bar{\eta}_{2} \phi(-h_{1}(x_{1})) \phi(-h_{2}(x_{2}))) \right] \\ &= \mathop{\mathbb{E}}_{\mathbf{z}} \left[c_{1} (\eta_{1} \phi(h_{1}(x_{1})) + \bar{\eta}_{1} \phi(-h_{1}(x_{1}) > 0)) (\eta_{2} \phi(h_{2}(x_{2})) + \bar{\eta}_{2} \phi(-h_{2}(x_{2}))) \right] \\ &= \mathop{\mathbb{E}}_{\mathbf{z}} \left[c_{1} C_{\phi}^{\eta_{1}}(h_{1}(x_{1})) C_{\phi}^{\eta_{2}}(h_{2}(x_{2})) \right], \end{split}$$

we can express $R_{\phi}(h_2)$ using the generic ϕ -conditional risk $C_{\phi}^{\eta}(\alpha)$. According to the definition of R_{ϕ}^* , we correspondingly have

$$R_{\phi}^* = \mathbb{E}\left[c_1 H_{\phi}(\eta_1) H_{\phi}(\eta_2)\right].$$

Similarly we can also express $R(h_2)$ and R^* as

$$R(h_2) = \mathop{\mathbb{E}}_{\mathbf{z}} [c_1 C^{\eta_1}(h_1(x_1)) C^{\eta_2}(h_2(x_2))]$$
$$R^* = \mathop{\mathbb{E}}_{\mathbf{z}} [c_1 H(\eta_1) H(\eta_2)],$$

where $C^{\eta}(\alpha)$ and $H(\eta)$ are defined by replacing ϕ with 1 in $C^{\eta}_{\phi}(\alpha)$ and $H_{\phi}(\eta)$. Note that $H(\eta)$ is always obtained when the sign of α is the same as the sign of $\eta - 1/2$.

Denote by α^* the signs of solutions {sign($\eta_1 - 1/2$), sign($\eta_2 - 1/2$)}. Then, we have

$$\begin{aligned} R(h_2) - R^* &= \mathop{\mathbb{E}}_{\mathbf{z}} \left[c_1 \left(C^{\eta_1}(h_1(x_1)) C^{\eta_2}(h_2(x_2)) - H(\eta_1) H(\eta_2) \right) \right] \\ &= \mathop{\mathbb{E}}_{\mathbf{z}} \left[c_1 \mathbb{1}(\operatorname{sign}(h) \neq \alpha^*) \left(C^{\eta_1}(h_1(x_1)) C^{\eta_2}(h_2(x_2)) - H(\eta_1) H(\eta_2) \right) \right] \end{aligned}$$

Since ψ is convex [1], it follows that

$$\psi(R(h_2) - R^*) \le \mathop{\mathbb{E}}_{\mathbf{z}} \left[c_1 \mathbb{1}(\operatorname{sign}(h) \neq \alpha^*) \psi\left(C^{\eta_1}(h_1(x_1)) C^{\eta_2}(h_2(x_2)) - H(\eta_1) H(\eta_2) \right) \right]$$

Without loss of generality, assume $\eta_1 \leq \bar{\eta}_1$ and $\eta_2 \leq \bar{\eta}_2$. Thus, according to the definition, $H(\eta_1) = \eta_1$ and $H(\eta_2) = \eta_2$. Then, we want to show that for any h_1, h_2 whose signs are not equivalent to α^* , we have

$$\psi\left(C^{\eta_1}(h_1(x_1))C^{\eta_2}(h_2(x_2)) - H(\eta_1)H(\eta_2)\right) \le H_{\phi}^-(\eta_1)H_{\phi}^-(\eta_2) - H_{\phi}(\eta_1)H_{\phi}(\eta_2).$$
(1)

To this end, we consider two cases: (1) only one classifier from h_1, h_2 makes the prediction that is opposite to α^* ; and (2) both h_1, h_2 make predictions that are opposite to α^* .

For Case (1), assume that h_1 makes the opposite prediction. Thus, $C^{\eta_1}(h_1(x_1)) = \bar{\eta}_1$, and $C^{\eta_2}(h_2(x_2)) = \eta_2$. Then, we have

$$\psi\left(C^{\eta_1}(h_1(x_1))C^{\eta_2}(h_2(x_2)) - H(\eta_1)H(\eta_2)\right) = \psi\left((\bar{\eta}_1 - \eta_1)\eta_2\right).$$

Based on Lemma 1, Part 1, it follows that

$$\psi((\bar{\eta}_1 - \eta_1)\eta_2) \le \eta_2 \psi(\bar{\eta}_1 - \eta_1) = \eta_2 \left(H_{\phi}^-(\eta_1) - H_{\phi}(\eta_1)\right).$$

Based on Lemma 1, Part 3, we have $\eta_2 \leq H_{\phi}(\eta_2)$. So it follows that

$$\psi((\bar{\eta}_1 - \eta_1)\eta_2) \le \left(H_{\phi}^-(\eta_1) - H_{\phi}(\eta_1)\right)H_{\phi}(\eta_2).$$

Based on Lemma 1, Part 2, we prove Eq. (1).

For Case (2), we have $C^{\eta_1}(h_1(x_1)) = \bar{\eta}_1$, and $C^{\eta_2}(h_2(x_2)) = \bar{\eta}_2$. Thus,

$$\psi\left(C^{\eta_1}(h_1(x_1))C^{\eta_2}(h_2(x_2)) - H(\eta_1)H(\eta_2)\right) = \psi\left(\bar{\eta}_1\bar{\eta}_2 - \eta_1\eta_2\right)$$

Without loss of generality, assume $\eta_1 \leq \eta_2$, i.e., $\bar{\eta}_2 \leq \bar{\eta}_1$. We have that

$$\begin{split} \bar{\eta}_1 \bar{\eta}_2 &- \eta_1 \eta_2 = \bar{\eta}_1 \bar{\eta}_2 - \eta_1 \eta_2 - \eta_1 \bar{\eta}_2 + \eta_1 \bar{\eta}_2 \\ &= \bar{\eta}_2 (\bar{\eta}_1 - \eta_1) + \eta_1 (\bar{\eta}_2 - \eta_2) \\ &\leq \bar{\eta}_1 (\bar{\eta}_1 - \eta_1) + \eta_1 (\bar{\eta}_2 - \eta_2). \end{split}$$
(2)

Since ψ is convex, we have

$$\begin{split} \psi \left(\bar{\eta}_1 \bar{\eta}_2 - \eta_1 \eta_2 \right) &\leq \psi \left(\bar{\eta}_1 (\bar{\eta}_1 - \eta_1) + \eta_1 (\bar{\eta}_2 - \eta_2) \right) \\ &\leq \bar{\eta}_1 \psi (\bar{\eta}_1 - \eta_1) + \eta_1 \psi (\bar{\eta}_2 - \eta_2). \end{split}$$

According to the definition of ψ , we have $\psi(\bar{\eta} - \eta) = H_{\phi}^{-}(\eta) - H_{\phi}(\eta)$. According to Lemma 1, Parts 4&3, we have $\bar{\eta}_{1} \leq 1 \leq H_{\phi}^{-}(\eta_{2}), \eta_{1} \leq H_{\phi}(\eta_{1})$. As a result, we have

$$\psi\left(\bar{\eta}_1\bar{\eta}_2 - \eta_1\eta_2\right) \le H_{\phi}^{-}(\eta_2)\left(H_{\phi}^{-}(\eta_1) - H_{\phi}(\eta_1)\right) + H_{\phi}(\eta_1)\left(H_{\phi}^{-}(\eta_2) - H_{\phi}(\eta_2)\right)$$

which proves Eq. (1).

Finally, we have

$$\begin{split} \psi(R(h_{2}) - R^{*}) &\leq \mathop{\mathbb{E}}_{\mathbf{z}} \left[c_{1} \mathbb{1}(\operatorname{sign}(h) \neq \alpha^{*}) \left(H_{\phi}^{-}(\eta_{1}) H_{\phi}^{-}(\eta_{2}) - H_{\phi}(\eta_{1}) H_{\phi}(\eta_{2}) \right) \right] \\ &\leq \mathop{\mathbb{E}}_{\mathbf{z}} \left[c_{1} \mathbb{1}(\operatorname{sign}(h) \neq \alpha^{*}) \left(C_{\phi}^{\eta_{1}}(h_{1}(x_{1})) C_{\phi}^{\eta_{2}}(h_{2}(x_{2})) - H_{\phi}(\eta_{1}) H_{\phi}(\eta_{2}) \right) \right] \\ &\leq \mathop{\mathbb{E}}_{\mathbf{z}} \left[c_{1} \left(C_{\phi}^{\eta_{1}}(h_{1}(x_{1})) C_{\phi}^{\eta_{2}}(h_{2}(x_{2})) - H_{\phi}(\eta_{1}) H_{\phi}(\eta_{2}) \right) \right] \\ &= R_{\phi}(h_{2}) - R_{\phi}^{*}. \end{split}$$

1.2 Extending to General Situations

We prove that Theorem 1 can be extended to h_3 , then, it can be similarly extended to any k. Note that the key is to prove

$$\psi\left(C^{\eta_1}(h_1(x_1))C^{\eta_2}(h_2(x_2))C^{\eta_3}(h_3(x_3)) - H(\eta_1)H(\eta_2)H(\eta_3)\right) \\ \leq H_{\phi}^{-}(\eta_1)H_{\phi}^{-}(\eta_2)H_{\phi}^{-}(\eta_3) - H_{\phi}(\eta_1)H_{\phi}(\eta_2)H_{\phi}(\eta_3).$$
(3)

Similarly, we consider three cases: (1) only one classifier from h_1, h_2, h_3 makes the prediction that is opposite to α^* ; (2) two classifiers from h_1, h_2, h_3 make predictions that are opposite to α^* ; and (3) all three classifiers make predictions that are opposite to α^* .

For Case (1), the proof is similar to that in Section 1.1.

For Case (2), assume that h_1, h_2 make the opposite predictions. Then, we have

$$\psi \left(C^{\eta_1}(h_1(x_1)) C^{\eta_2}(h_2(x_2)) C^{\eta_3}(h_3(x_3)) - H(\eta_1) H(\eta_2) H(\eta_3) \right) = \psi \left(\left(\bar{\eta}_1 \bar{\eta}_2 - \eta_1 \eta_2 \right) \eta_3 \right) \le \eta_3 \psi \left(\bar{\eta}_1 \bar{\eta}_2 - \eta_1 \eta_2 \right).$$

Thus, based on Eq. (1), we can prove Eq. (3).

For Case (3), without loss of generality, assume that $\eta_1 \leq \eta_2 \leq \eta_3$, i.e., $\bar{\eta}_3 \leq \bar{\eta}_2 \leq \bar{\eta}_1$. Then, we have

$$\begin{split} \psi \left(C^{\eta_1}(h_1(x_1)) C^{\eta_2}(h_2(x_2)) C^{\eta_3}(h_3(x_3)) - H(\eta_1) H(\eta_2) H(\eta_3) \right) \\ &= \psi \left(\bar{\eta}_1 \bar{\eta}_2 \bar{\eta}_3 - \eta_1 \eta_2 \eta_3 \right) \\ &= \psi \left(\bar{\eta}_3 (\bar{\eta}_1 \bar{\eta}_2 - \eta_1 \eta_2) + \eta_1 \eta_2 (\bar{\eta}_3 - \eta_3) \right). \end{split}$$

Based on Eq. (2), it follows that

$$\begin{split} \psi \left(\bar{\eta}_3(\bar{\eta}_1 \bar{\eta}_2 - \eta_1 \eta_2) + \eta_1 \eta_2(\bar{\eta}_3 - \eta_3) \right) \\ &= \psi \left(\bar{\eta}_3 \bar{\eta}_2(\bar{\eta}_1 - \eta_1) + \bar{\eta}_3 \eta_1(\bar{\eta}_2 - \eta_2) + \eta_1 \eta_2(\bar{\eta}_3 - \eta_3) \right) \\ &\leq \psi \left(\bar{\eta}_1 \bar{\eta}_2(\bar{\eta}_1 - \eta_1) + \bar{\eta}_2 \eta_1(\bar{\eta}_2 - \eta_2) + \eta_1 \eta_2(\bar{\eta}_3 - \eta_3) \right) \\ &\leq \bar{\eta}_1 \bar{\eta}_2 \psi \left(\bar{\eta}_1 - \eta_1 \right) + \bar{\eta}_2 \eta_1 \psi \left(\bar{\eta}_2 - \eta_2 \right) + \eta_1 \eta_2 \psi \left(\bar{\eta}_3 - \eta_3 \right) \end{split}$$

Then, since $\bar{\eta}_1 \leq 1 \leq H_{\phi}^-(\eta_2), \bar{\eta}_2 \leq 1 \leq H_{\phi}^-(\eta_3), \eta_1 \leq H_{\phi}(\eta_1), \eta_2 \leq H_{\phi}(\eta_2)$, it follows that

$$\begin{split} \bar{\eta}_1 \bar{\eta}_2 \psi \left(\bar{\eta}_1 - \eta_1 \right) + \bar{\eta}_2 \eta_1 \psi \left(\bar{\eta}_2 - \eta_2 \right) + \eta_1 \eta_2 \psi \left(\bar{\eta}_3 - \eta_3 \right) \\ &\leq H_{\phi}^-(\eta_2) H_{\phi}^-(\eta_3) \left(H_{\phi}^-(\eta_1) - H_{\phi}(\eta_1) \right) + H_{\phi}^-(\eta_3) H_{\phi}(\eta_1) \left(H_{\phi}^-(\eta_2) - H_{\phi}(\eta_2) \right) \\ &\quad + H_{\phi}(\eta_1) H_{\phi}(\eta_2) \left(H_{\phi}^-(\eta_3) - H_{\phi}(\eta_3) \right) \\ &= H_{\phi}^-(\eta_1) H_{\phi}^-(\eta_2) H_{\phi}^-(\eta_3) - H_{\phi}(\eta_1) H_{\phi}(\eta_2) H_{\phi}(\eta_3), \end{split}$$

which proves the Eq. (3).

References

[1] Peter L Bartlett, Michael I Jordan, and Jon D McAuliffe. Convexity, classification, and risk bounds. *Journal of the American Statistical Association*, 101(473):138–156, 2006.