

1 We thank reviewers for their efforts and insightful suggestions. In this work, we proposed an all-way Boolean Tensor  
2 Decomposition (BTD) method, GETF, by incorporating the geometric property of Boolean tensor data. We are  
3 encouraged that reviewers find our theoretical driven method effective and efficient, which provides a state-of-the-art  
4 way to solve an important problem. In the following, we answer the main questions and comments from the reviewers.  
5 We will also polish the paper writing to address all the minor issues pointed out by reviewers.

6 To **Reviewer #1, Q1** [...why binary representation is better than count representation...]. We think that both binary  
7 representation and count representation have their own merits and how to select the representation should depend  
8 on applications. In this work, we tackle the tensor decomposition problem in Boolean tensors and thus casting the  
9 crime dataset as a binary representation to indicate whether a crime has happened (1) or not (0) is the best choice to  
10 demonstrate our effectiveness. The proposed methods can also be applied to more general scenarios, such as knowledge  
11 graph, contextual recommender systems, search engine and high-dimensional spatial data modeling. **Q3** [...What is the  
12 convergence tolerance?...]. Task completion for experiments is defined as achieving the convergence criteria, presented  
13 in Appendix line 171. And yes, the number of patterns is fixed as 5. We will polish the writing in the revised version to  
14 make it clear. **Q4** [...the y-axis in Figures Figure 7C and 7D is the same...]. The y-axis of Fig 7C-E are not the same.  
15 Definition of crime index/dates/counts are in the Appendix 4.2. GETF distinguishes the safe and dangerous regions by  
16 reconstructing the relational patterns of crimes, which forms a Boolean relational tensor data (region-date-year), on  
17 which GETF showed better performance over baselines.

18 To **Reviewer #1, Q2** [...Why not showing the scalability of GETF and other baselines...] and **Reviewer #4, Q1** [...No  
19 comparisons with other methods were given...]. In Fig 6 and Appendix Fig 4, we compared GETF with SOTA baselines  
20 on reconstruction error along with the increase of dimensions on different tensor scale, density (corresponds to non-zeros,  
21 Fig 6A-B,G-H) and noise. Due to the page limit, we have to put detailed scalability experiments on real world datasets  
22 in Appendix 4.1, 4.2 and 4.3 (Appendix Figure 7,10), and we apologize for leading to this misunderstanding.

23 To **Reviewer #2, Q1** [...It would be good if the paper provides theoretical analysis...]. Thanks for the suggestion, we  
24 will work on this direction in the future.

25 To **Reviewer #2, Q2** [...none of the existing algorithms are designed to handle the HBTD problem for higher order  
26 tensors...] and **Reviewer #3, Q4** [...While alternating optimization methods have not been written...]. Thanks for  
27 pointing this out, and we agree that LOM can be theoretically extended to higher order. However, LOM's Bayesian  
28 fitting scheme is too heavy on computational cost for most higher-order tensors. Empirically, LOM took an hour to  
29 converge on 3D data with 500 features on each dimension (Appendix Fig 5D). Increasing data dimension usually results  
30 in 2 magnitude of increase in data size, yet LOM will fail to converge. In terms of the alternative optimization, besides  
31 the high space/computation cost by Khatri-Rao product for the matricization of higher order tensor, the updating process  
32 is already above  $O(n)$  complexity on each dimensionality. For the noisy tensor, this usually results in excessive updating  
33 for this NP-hard problem. Partition the matricization could save some computations, but with a price of increased space  
34 complexity (Park et al ICDE2017). For fair comparisons, we compared our methods on 2D with MP and 3D with LOM,  
35 representing SOTA methods. But for higher order (4D, 5D), we showed the performance of GETF without comparison  
36 as all baseline methods failed to converge on such moderate sized higher order tensors.

37 To **Reviewer #2, Q4** [...Does it need all permutations...] and **Reviewer #3, Q1** [...finding the right permutations up to  
38 a  $(k-1)$  LTL tensor...]. The existence of  $(k-1)$ -LTL IRT for any tensor is given in line 154-156, and its uniqueness is  
39 supported by Lemma 3 (proof is in Appendix). Not all permutations of IRT are needed to achieve the  $(k-1)$ -LTL tensor.

40 To **Reviewer #3, Q2** [...a  $(k-1)$  LTL tensor and then its closest flat 2-LTL tensor...The existence of such tensor for any  
41 tensor is not assured]. GETF is designed based on the geometric property of Boolean tensor, where in a flat 2-LTL  
42 tensor, the largest pattern tensor resides on the  $1/k$  segmentation point (Lemma1 Fig 2). Lemma 3 and 4 indicate the  
43  $(k-1)$ -LTL IRT is the closest form to 2-LTL IRT. Even the 2-LTL IRT does not always exist, Lemma 2 indicates when  
44 a tensor is sparse and its largest pattern tensor is distinct, the pattern tensor can be sub-optimally detected by the flat  
45 2-LTL tensor with largest solid overlap with the unique  $(k-1)$ -LTL IRT. Noted, there are at most  $n$  flat 2-LTL tensors  
46 needed to be considered, here  $n$  is the tensor size.

47 To **Reviewer #2, Q3** [I actually have doubts on the efficiency of this step] and **Reviewer #3, Q3** [...it may be  
48 computationally demanding...]. For a  $n = m^k$  size tensor, since  $(k-1)$ -LTL IRT is unique and there are at most  $n$  flat  
49 2-LTL tensors to be considered, the 2-LTL\_project is  $O(n)$ . The complexity cost of the Pattern\_fiber\_finding algorithm  
50 is  $\frac{m^{k+1}-m}{m-1} + km \log(m)$ . On top of the identified pattern fiber, the Geometric\_folding (Fig 5, main 3.4, Appendix  
51 3.6) algorithm recovered the rank 1 tensor by applying Pattern\_fiber\_finding sequentially that has a complexity cost  
52 at  $\frac{m^{k+2}-m^2}{(m-1)^2} - \frac{km}{m-1} + \frac{k(k+1)}{m-1} + \frac{k(k+1)}{2} m \log(m) \sim O(m^k)$ , which explained the computational efficiency of GETF.  
53 Moreover, the additional space complexity for GETF is  $\frac{m^k-m}{m-1}$ , also  $O(n)$ . We highlighted the complexity analysis in  
54 main text Section 3.5 and will provide detailed derivation of complexity in the revised Appendix.