

1 We thank the reviewers for their critical assessment of our work, and for the overall positive reception. Below we reply  
2 to each review to clarify points and provide additional insights into the problem and methods, which we hope will better  
3 highlight the technical novelty and contribution of our work.

#### 4 **Reviewer 1**

- 5 • To the first point in weaknesses. We agree on this important point and we use cross-validation to verify this  
6 assumption. For instance, in our real-world applications (described below for R2), the model fit of LCE-A is much  
7 better than other models. Note also that the ABR simulator uses real throughput traces and video data, and the results  
8 there indicate a robustness of assuming a shared spatial kernel.
- 9 • To the second point. Thanks for raising this! The number of parameters is  $(1 + m) \times C + d + m$  for embedding  
10 dimension  $m$ . Although LCE-A has more parameters, the model complexity is not necessarily higher. The kernel  
11  $k^z(E(c), E(c'))$  imposes regularization in the model and encourages correlations across component functions. Lines  
12 124–128 in Sec 2.2 discuss the connection between the regularization of a GP prior and the function norm in the  
13 RKHS. With stronger correlation there is a larger norm and more regularization. We will clarify this in the paper.

#### 14 **Reviewer 2**

- 15 • To the first point in comments. Thanks for asking! We have applied this method to two real problems: 1) tuning a  
16 live video playback controller under different connection qualities, to minimize stall time while maintaining high  
17 quality. There are 6 controller parameters and 5 connection qualities (from excellent to poor). 2) tuning data fetch  
18 parameters for an app surface, contextualized for different countries and connection types (4g, wifi, etc). The goal  
19 was to reduce data utilization without affecting app performance. For both problems, performance metrics had to be  
20 evaluated by A/B tests that took several days (though multiple design points could be run in parallel). Metrics could  
21 not be logged at the level of context, meaning typical contextual BO methods could not be used. For both problems,  
22 the LCE-A model had the best cross-validation performance and so was used for the optimization. LCE-A found the  
23 best policy compared with random search and standard BO, and significantly improved system performance.
- 24 • To the second point. The embedding sizes are set to be 1 in the simulation studies. If LCE-A fails to learn the  
25 embedding and the corresponding correlation structure, then it essentially falls back to SAC, which doesn't borrow  
26 strength across contexts; we will add discussion of this. As noted, when possible, pre-training can accelerate learning  
27 in the small-data regime, and is something we will investigate in future work.
- 28 • The two context buckets have very different network conditions and their bandwidths are unstable; thus the QoEs  
29 have larger variances. We will clarify this in the paper.
- 30 • Thanks for the suggestion in related work! We will add this into the discussion. Our work assumes an additive  
31 structure of component functions and fits nicely into the framework of grey-box BO  $g(h(\mathbf{x}))$ . Here,  $g$  is an additive  
32 function and  $h$  consists of unknown context functions which are learnt via the new LCE kernel.

#### 33 **Reviewer 3**

- 34 • Thanks for the reference [TSC11]! We were unaware of this paper, but it is indeed related and our work nicely  
35 extends the methods developed there. Eqn. (1) of TSC11 is the problem that we solve as well. When using the  
36 LCE-A and SAC kernel, the acquisition function was the same as their expected policy score improvement. Our work  
37 extends TSC11 by handling the situation where the outcomes  $f(x_e, x)$  (i.e.  $f_c(x_c)$  in our paper) are not observable  
38 under each environment (i.e. context) separately. We show how to optimize Eqn. (1) of TSC11 when given only  
39 total score, which is critical for settings where the controller operates across heterogeneous environments and score  
40 cannot be easily attributed to each (the notorious credit assignment problem). We will add discussion of TSC11 and  
41 its area of work, and we believe that the connection to it broadens and strengthens the technical contribution of our  
42 paper. We hope that clarifying this point has made the contribution of our work more apparent.
- 43 • On policy performance in easy/difficult contexts. In our simulation studies, the easy contexts are the dense contexts  
44 with the majority of the weight and the difficult contexts are the sparse contexts with small weights. We show that  
45 LCE-A improves performance in difficult contexts by learning the context correlation structure, e.g. in Fig. 4(b).
- 46 • To the second question in comments. In our current studies, embeddings are learnt similar to inferring the matrix  $B$   
47 inside an ICM kernel by maximizing likelihood. We will clarify this.

#### 48 **Reviewer 11**

- 49 • Thanks for your suggestions on improving organization of the paper! For Q3, the matrix  $B$  is estimated by maximizing  
50 marginal likelihood, as is typical for multi-task GP fitting.
- 51 • For Q4, the struggle BO has with high dimensions is with the number of parameters in the feature space. That is  
52 remaining constant across these models. LCE-M does have additional hyperparameters, but these tend to increase  
53 regularization and do not cause problems of the sort faced by high-dimensional BO (see response to R1).