
Near-Isometry by Relaxation: Supplement

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1 Proof of Proposition 1,3.

We first prove the following Lemma.

Proposition 1. *If $f : S \subseteq \mathbb{R}^D \rightarrow \mathbb{R}$ is convex, non-negative and $\nabla^2 f$ exists for all $x \in \text{int } S$, then $\frac{1}{2}f^2(x)$ is convex.*

Proof $\nabla(\frac{1}{2}f^2) = f\nabla f$; $\nabla^2(\frac{1}{2}f^2) = f\nabla^2 f + \nabla f\nabla f'$ which is positive definite whenever $f\nabla^2 f$ is. \square .

Using the above Lemma, and the fact that $\|\mathbf{H}_k - \mathbf{I}_n\|$ is non-negative and infinitely differentiable almost everywhere, we obtain the desired result. \square

2 Proof of Proposition 2

$$\|\mathbf{G}\|_{\mathbf{G}_0 + \epsilon \mathbf{I}_s} = \sup_{u \neq 0} \frac{u^T \mathbf{G} u}{u^T \mathbf{G}_0 u + \epsilon \|u\|^2} \quad (1)$$

$$= \sup_{u \neq 0} \frac{v^T \mathbf{G}_\epsilon^{-1} \mathbf{G} \mathbf{G}_\epsilon^{-1} v}{\|v\|^2} \quad \text{with } \mathbf{G}_\epsilon = (\mathbf{G}_0 + \epsilon \mathbf{I})^{1/2} \text{ and } v = \mathbf{G}_\epsilon u \quad (2)$$

$$= \|\tilde{\mathbf{G}}\|_2 \quad \text{with } \tilde{\mathbf{G}} = (\mathbf{G}_0 + \epsilon \mathbf{I})^{-1/2} \mathbf{G} (\mathbf{G}_0 + \epsilon \mathbf{I})^{-1/2} \quad (3)$$

For (2), we first prove the following fact

$$\sup_{u \in \mathbb{R}^s} \frac{|u^T \mathbf{G} u|}{u^T \mathbf{G}_0 u + \epsilon \|u\|^2} \begin{cases} = \sup_{u \in \text{Null } \mathbf{G}^+} \frac{|u^T \mathbf{G} u|}{u^T \mathbf{G}_0 u + \epsilon \|u\|^2} & \text{if } \text{Null}(\mathbf{G}) = \text{Null}(\mathbf{G}_0) \\ \leq \max_{\alpha^2 + \beta^2 = 1} \frac{\beta^2 \lambda^1(\mathbf{G}) + \alpha^2 \lambda_{\max}(\mathbf{G}) + 2\alpha\beta \Theta_{\max}(\mathbf{G}, \mathbf{G}_0)}{\beta^2 \epsilon + \alpha^2 (\lambda_{\min}^*(\mathbf{G}_0) + \epsilon)} & \text{if } \text{Null}(\mathbf{G}) \neq \text{Null}(\mathbf{G}_0) \end{cases} \quad (4)$$

where $\lambda_{\max}(\mathbf{G})$ is the spectral radius of \mathbf{G} , $\Theta(\mathbf{G}, \mathbf{G}_0) = \sup_{\|u\|=\|v\|=1, v \in \text{Null } \mathbf{G}, u \in \text{Null } \mathbf{G}_0} u^T \mathbf{G} v$ is the cosine of the principal angle between $\text{Null } \mathbf{G}$ and $\text{Null } \mathbf{G}_0$, and $\lambda_{\min}^*(\mathbf{G}_0)$ is the smallest non-zero eigenvalue of \mathbf{G}_0 .

Denote for simplicity $g(u) = \frac{|u^T \mathbf{G} u|}{u^T \mathbf{G}_0 u + \epsilon \|u\|^2}$. (1) If $\text{Null}(\mathbf{G}) = \text{Null}(\mathbf{G}_0)$ then for $u \in \text{Null } \mathbf{G}$ the value is 0, which cannot be the sup. Let $u_1 = v \oplus u_0$ with $u_0 \in \text{Null } \mathbf{G}$, $v \in \text{Null } \mathbf{G}^\perp$. Then $u_1^T \mathbf{G}_0 u_1 + \epsilon \|u_1\|^2 = v^T \mathbf{G}_0 v + \epsilon (\|v\|^2 + \|u_0\|^2) > v^T \mathbf{G}_0 v + \epsilon \|v\|^2$. Hence, the u which attains the supremum must be in $\text{Null } \mathbf{G}$.

Now note that, if $\text{Null } \mathbf{G} \neq \text{Null } \mathbf{G}_0$, $\mathbb{R}^s = \text{Null } \mathbf{G}_0 \oplus \text{Null } \mathbf{G}_0^\perp$, and $\text{Null } \mathbf{G} = (\text{Null } \mathbf{G}_0 \cap \text{Null } \mathbf{G}) \oplus \mathcal{V}$, with \mathcal{V} the orthogonal complement of $\text{Null } \mathbf{G}_0 \cap \text{Null } \mathbf{G}$ in $\text{Null } \mathbf{G}_0$ and the supremum of $g(u) =$ is attained on $\mathcal{U} = \mathcal{V} \oplus \text{Null } \mathbf{G}_0^\perp$ (as adding any component along the orthogonal complement of this space only adds a positive value to the denominator, increasing $g(u)$). Any $u \in \mathcal{U}$ can be written as $u = \alpha u_0 \oplus \beta v_0$ with $u_0 \in \text{Null } \mathbf{G}_0^\perp$ and $v_0 \in \mathcal{V}$ unit vectors. By upper bounding every term in

the numerator and lower bounding $u_0' \mathbf{G}_0 u_0$ we obtain the result. Note that for ϵ small enough, the expression in 4 is close to $\frac{1}{\epsilon} \lambda^\dagger(\mathbf{G})$.

For (2), let $v \in \mathcal{V}$ and compute $g(v)$ as above, with $\alpha = 0$. It follows that $g(v) = \frac{|v' \mathbf{G} v|}{\epsilon \|v\|^2}$ and by taking the supremum over $v \in \mathcal{V}$ we obtain that $\sup_{\mathcal{V}} g(v) = \frac{1}{\epsilon} \lambda^\dagger(\mathbf{G}) < r$, from which the result follows.

For (3), it is obvious that when $\epsilon \rightarrow 0$, $g(v) \rightarrow \infty$ on \mathcal{V} , but remains finite for $u \notin \mathcal{V}$. More precisely, $\|\mathbf{G}\|_{\mathbf{G}_0} = \infty$ iff $\text{Null } \mathbf{G}_0 \not\subseteq \mathbf{G}$. To verify that $\|\cdot\|_{\mathbf{G}_0}$ is a norm, we must verify the triangle inequality, since the other two properties obviously hold. If $\|\mathbf{A}\|_{\mathbf{G}_0} = \infty$ or $\|\mathbf{B}\|_{\mathbf{G}_0} = \infty$, triangle inequality holds trivially. Assume then that $\|\mathbf{A}\|_{\mathbf{G}_0}, \|\mathbf{B}\|_{\mathbf{G}_0} < \infty$. Since $\|\mathbf{A}\|_{\mathbf{G}_0 + \epsilon \mathbf{I}_s} + \|\mathbf{B}\|_{\mathbf{G}_0 + \epsilon \mathbf{I}_s} \geq \|\mathbf{A} + \mathbf{B}\|_{\mathbf{G}_0 + \epsilon \mathbf{I}_s}$ for every $\epsilon > 0$, then in the limit we will have that $\|\mathbf{A}\|_{\mathbf{G}_0} + \|\mathbf{B}\|_{\mathbf{G}_0} \geq \|\mathbf{A} + \mathbf{B}\|_{\mathbf{G}_0}$.

The norm for comparing Riemannian metric The norm of a bilinear functional $f : \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}$ is defined as $\sup_{\|u\|=\|v\|=1} |f(u, v)|$, or since for a fixed orthonormal base of \mathbb{R}^s $f(u, v) = u' \mathbf{A} v$, $\|f\| = \sup_{\|u\|=\|v\|=1} |u' \mathbf{A} v|$. If \mathbf{A} is hermitian, then $\|f\| = \max \lambda(\mathbf{A})$ where $\lambda(\mathbf{A})$ denotes the spectrum of \mathbf{A} . One can define the norm with respect to any metric \mathbf{G}_0 on \mathbb{R}^s where \mathbf{G}_0 is a symmetric, positive definite matrix by $\|f\|_{\mathbf{G}_0} = \sup_{\|u\|_{\mathbf{G}_0}=\|v\|_{\mathbf{G}_0}=1} |u' \mathbf{A} v| = \sup_{\|\tilde{u}\|=\|\tilde{v}\|=1} |\tilde{u}' \mathbf{G}_0^{-1/2} \mathbf{A} \mathbf{G}_0^{-1/2} \tilde{v}| = \max \lambda_{(\mathbf{G}_0^{-1/2} \mathbf{A} \mathbf{G}_0^{-1/2})} |\lambda_i|$ In other words, the appropriate operator norm we seek can be expressed as a (generalized) matrix spectral norm. In our cases $\mathbf{G}_0 = \mathbf{I}_d$ and $\mathbf{A} = \mathbf{H}_k - \mathbf{I}_d$

3 Proof of Propositions 3

Note that we can write the loss as:

$$\sum_{k=1}^n \left\| \frac{1}{2} \mathbf{\Pi}'_k \mathbf{Y}' \mathbf{L}_k \mathbf{Y} \mathbf{\Pi}_k - \mathbf{\Pi}_k \mathbf{U}_k \mathbf{U}_k \mathbf{\Pi}_k \right\|_2^2$$

Where $\mathbf{\Pi}_k = (\mathbf{U}_k \mathbf{U}'_k + (\epsilon_{orth})_k \mathbf{I}_s)^{-1/2}$. We take the $\mathbf{\Pi}_k$ matrices to be fixed and don't depend on the data points \mathbf{Y} (in practice they do, however, after taking a gradient step we update the $\mathbf{\Pi}_k$ in an E-M style algorithm). Since $\mathbf{U}_k \mathbf{U}'_k$ and $\mathbf{\Pi}_k$ are the identity matrix (the latter multiplied by $1/(1 + \epsilon_{orth})$) when $s = d$ we can compute the derivative when $s > d$ without loss of generality.

3.1 Proof of Derivative

Since the derivative is a linear operator it's sufficient to show that the derivative of a single loss function is of the form:

$$\frac{\partial l_k}{\partial \mathbf{Y}} = (2|\lambda_k^*|) \text{sgn}(\lambda_k^*) \mathbf{L}_k \mathbf{Y} \mathbf{\Pi}_k \mathbf{u}_k \mathbf{u}'_k \mathbf{\Pi}'_k$$

To compute the derivative we will make use of the chain rule. First define the function l_k as a composition of functions:

$$l_k(\mathbf{Y}) \equiv \rho(P_k(H_k(\mathbf{Y})) - \mathbf{C}_k)$$

With $\mathbf{C}_k = \mathbf{\Pi}_k \mathbf{U}_k \mathbf{U}_k \mathbf{\Pi}_k$ and

$$\rho(\mathbf{U}) = (\max_k |\lambda_k(\mathbf{U})|)^2$$

$$P_k(\mathbf{H}) = \mathbf{\Pi}'_k \mathbf{H} \mathbf{\Pi}_k$$

$$H_k(\mathbf{Y}) = \frac{1}{2} \mathbf{Y}' \mathbf{L}_k \mathbf{Y}$$

Where \mathbf{U}, \mathbf{H} are both symmetric. Here we note that the matrix spectral norm reduces to the spectral radius if \mathbf{U} is symmetric. Since $H_k(\mathbf{Y})$ is defined to be symmetric and \mathbf{C}_k is symmetric this is the case. By the chain rule:

$$Dl_k(\mathbf{Y}) = D\rho(P_k(H_k(\mathbf{Y})) - \mathbf{C}_k) DP_k(H_k(\mathbf{Y})) DH_k(\mathbf{Y})$$

Taking these from left to right:

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3.1.1 $D\rho$

Since ρ is defined to be the largest (in absolute value) eigenvalue of \mathbf{U} (squared) the derivative¹ is the kronecker product between the corresponding eigenvector and itself multiplied by the sign of the eigenvalue:

$$D\sqrt{\rho(\mathbf{U})} = \text{sgn}(\lambda_k^*)(\mathbf{u}'_k \otimes \mathbf{u}'_k)$$

Where $|\lambda_k^*| = \sqrt{\rho(\mathbf{U})}$ and $\mathbf{U}\mathbf{u}_k = \lambda_k^*\mathbf{u}_k$ Then since we square the spectral radius we add the factor of $(2|\lambda_k^*|)$ so that:

$$D(\rho(\mathbf{U})) = (2|\lambda_k^*|)\text{sgn}(\lambda_k^*)(\mathbf{u}'_k \otimes \mathbf{u}'_k)$$

3.1.2 DP_k

$$DP_k(\mathbf{H}) = (\mathbf{\Pi}'_k \otimes \mathbf{\Pi}'_k)$$

Proof.

$$\begin{aligned} P_k(\mathbf{H}) &= \mathbf{\Pi}'_k \mathbf{H} \mathbf{\Pi}_k \\ dP_k(\mathbf{H}) &= \mathbf{\Pi}'_k d\mathbf{H} \mathbf{\Pi}_k \\ \Rightarrow \text{vec}(dP_k(\mathbf{H})) &= \text{vec}(\mathbf{\Pi}'_k d\mathbf{H} \mathbf{\Pi}_k) \\ &= (\mathbf{\Pi}'_k \otimes \mathbf{\Pi}'_k) d\text{vec}(\mathbf{H}) \end{aligned}$$

□

3.1.3 DH_k

$$DH_k(\mathbf{Y}) = \mathbf{N}_s(\mathbf{I}_s \otimes \mathbf{Y}'\mathbf{L}_k)$$

Where $\mathbf{N}_s = \mathbf{I}_{s^2} + \mathbf{K}_{ss}$ for \mathbf{K}_{ss} the commutation matrix defined in Magnus & Neudecker ch. 3 §7.

Proof.

$$\begin{aligned} H_k(\mathbf{Y}) &= \frac{1}{2} \mathbf{Y}'\mathbf{L}_k \mathbf{Y} \\ \Rightarrow dH_k(\mathbf{Y}) &= \frac{1}{2} [(d\mathbf{Y})'\mathbf{L}_k \mathbf{Y} + \mathbf{Y}'\mathbf{L}_k d\mathbf{Y}] \\ \Rightarrow \text{vec}(dH_k(\mathbf{Y})) &= \frac{1}{2} [(\mathbf{Y}'\mathbf{L}'_k \otimes \mathbf{I}_s) d\text{vec}(\mathbf{Y}) + (\mathbf{I}_s \otimes \mathbf{Y}'\mathbf{L}_k) d\text{vec}(\mathbf{Y})] \\ &= \frac{1}{2} [(\mathbf{Y}'\mathbf{L}'_k \otimes \mathbf{I}_s) \mathbf{K}_{ns} d\text{vec}(\mathbf{Y}) + (\mathbf{I}_s \otimes \mathbf{Y}'\mathbf{L}_k) d\text{vec}(\mathbf{Y})] \\ &= \frac{1}{2} [\mathbf{K}_{ss}(\mathbf{I}_s \otimes \mathbf{Y}'\mathbf{L}'_k) d\text{vec}(\mathbf{Y}) + (\mathbf{I}_s \otimes \mathbf{Y}'\mathbf{L}_k) d\text{vec}(\mathbf{Y})] \\ &= \frac{1}{2} [(\mathbf{K}_{ss} + \mathbf{I}_{s^2})(\mathbf{I}_s \otimes \mathbf{Y}'\mathbf{L}_k) d\text{vec}(\mathbf{Y})] \\ &= \frac{1}{2} [2\mathbf{N}_s(\mathbf{I}_s \otimes \mathbf{Y}'\mathbf{L}_k) d\text{vec}(\mathbf{Y})] \\ &= \mathbf{N}_s(\mathbf{I}_s \otimes \mathbf{Y}'\mathbf{L}_k) d\text{vec}(\mathbf{Y}) \end{aligned}$$

\mathbf{L}_k is symmetric

□

3.1.4 Dc_k

Putting it all together

$$Dc_k(\mathbf{Y}) = (2|\lambda_k^*|)\text{sgn}(\lambda_k^*)(\mathbf{u}'_k \otimes \mathbf{u}'_k)(\mathbf{\Pi}'_k \otimes \mathbf{\Pi}'_k)\mathbf{N}_s(\mathbf{I}_s \otimes \mathbf{Y}'\mathbf{L}_k) = \text{vec}\left(\frac{\partial c_k}{\partial \mathbf{Y}}\right)'$$

¹see Matrix Differential Calculus With Applications in Statistics And Economics by Magnus & Neudecker ch. 9 §12 for proof

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We can simplify this to get the claim:

$$\frac{\partial c_k}{\partial Y} = (2|\lambda_k^*|) \text{sgn}(\lambda_k^*) \mathbf{L}_k \mathbf{Y} \mathbf{\Pi}_k \mathbf{u}_k \mathbf{u}'_k \mathbf{\Pi}'_k$$

Proof.

$$\begin{aligned} Dc_k(\mathbf{Y}) &= (2|\lambda_k^*|) \text{sgn}(\lambda_k^*) (\mathbf{u}'_k \otimes \mathbf{u}'_k) (\mathbf{\Pi}'_k \otimes \mathbf{\Pi}'_k) \mathbf{N}_s (\mathbf{I}_s \otimes \mathbf{Y}' \mathbf{L}_k) \\ &= (2|\lambda_k^*|) \text{sgn}(\lambda_k^*) (\mathbf{u}'_k \otimes \mathbf{u}'_k) (\mathbf{\Pi}'_k \otimes \mathbf{\Pi}'_k) \frac{1}{2} (\mathbf{K}_{ss} + \mathbf{I}_{s^2}) (\mathbf{I}_s \otimes \mathbf{Y}' \mathbf{L}_k) \\ &= (2|\lambda_k^*|) \text{sgn}(\lambda_k^*) \frac{1}{2} (\mathbf{u}'_k \mathbf{\Pi}'_k \otimes \mathbf{u}'_k \mathbf{\Pi}'_k) (\mathbf{K}_{ss} + \mathbf{I}_{s^2}) (\mathbf{I}_s \otimes \mathbf{Y}' \mathbf{L}_k) \\ &= (2|\lambda_k^*|) \text{sgn}(\lambda_k^*) \frac{1}{2} [(\mathbf{u}'_k \mathbf{\Pi}'_k \otimes \mathbf{u}'_k \mathbf{\Pi}'_k) \mathbf{K}_{ss} (\mathbf{I}_s \otimes \mathbf{Y}' \mathbf{L}_k) + (\mathbf{u}'_k \mathbf{\Pi}'_k \otimes \mathbf{u}'_k \mathbf{\Pi}'_k) (\mathbf{I}_s \otimes \mathbf{Y}' \mathbf{L}_k)] \\ &= (2|\lambda_k^*|) \text{sgn}(\lambda_k^*) \frac{1}{2} [(\mathbf{u}'_k \mathbf{\Pi}'_k \otimes \mathbf{u}'_k \mathbf{\Pi}'_k) (\mathbf{Y}' \mathbf{L}_k \otimes \mathbf{I}_s) \mathbf{K}_{ns} + (\mathbf{u}'_k \mathbf{\Pi}'_k \otimes \mathbf{u}'_k \mathbf{\Pi}'_k) (\mathbf{I}_s \otimes \mathbf{Y}' \mathbf{L}_k)] \\ &= (2|\lambda_k^*|) \text{sgn}(\lambda_k^*) \frac{1}{2} [(\mathbf{u}'_k \mathbf{\Pi}'_k \mathbf{Y}' \mathbf{L}_k \otimes \mathbf{u}'_k \mathbf{\Pi}'_k) \mathbf{K}_{ns} + (\mathbf{u}'_k \mathbf{\Pi}'_k \otimes \mathbf{u}'_k \mathbf{\Pi}'_k \mathbf{Y}' \mathbf{L}_k)] \\ &= (2|\lambda_k^*|) \text{sgn}(\lambda_k^*) \frac{1}{2} [\mathbf{K}_{11} (\mathbf{u}'_k \mathbf{\Pi}'_k \otimes \mathbf{u}'_k \mathbf{\Pi}'_k \mathbf{Y}' \mathbf{L}_k) + (\mathbf{u}'_k \mathbf{\Pi}'_k \otimes \mathbf{u}'_k \mathbf{\Pi}'_k \mathbf{Y}' \mathbf{L}_k)] \\ &= (2|\lambda_k^*|) \text{sgn}(\lambda_k^*) (\mathbf{u}'_k \mathbf{\Pi}'_k \otimes \mathbf{u}'_k \mathbf{\Pi}'_k \mathbf{Y}' \mathbf{L}_k) \quad \mathbf{K}_{11} = 1 \\ &= (2|\lambda_k^*|) \text{sgn}(\lambda_k^*) (\mathbf{\Pi}_k \mathbf{u}_k \otimes \mathbf{L}_k \mathbf{Y} \mathbf{\Pi}_k \mathbf{u}_k)' \end{aligned}$$

Then note that:

$$\begin{aligned} \text{vec}((2|\lambda_k^*|) \text{sgn}(\lambda_k^*) \mathbf{L}_k \mathbf{Y} \mathbf{\Pi}_k \mathbf{u}_k \mathbf{u}'_k \mathbf{\Pi}'_k) &= (2|\lambda_k^*|) \text{sgn}(\lambda_k^*) \text{vec}([\mathbf{L}_k \mathbf{Y} \mathbf{\Pi}_k \mathbf{u}_k][1][\mathbf{u}'_k \mathbf{\Pi}'_k]) \\ &= (2|\lambda_k^*|) \text{sgn}(\lambda_k^*) (\mathbf{\Pi}_k \mathbf{u}_k \otimes \mathbf{L}_k \mathbf{Y} \mathbf{\Pi}_k \mathbf{u}_k) \text{vec}(1) \\ &= (2|\lambda_k^*|) \text{sgn}(\lambda_k^*) (\mathbf{\Pi}_k \mathbf{u}_k \otimes \mathbf{L}_k \mathbf{Y} \mathbf{\Pi}_k \mathbf{u}_k) \\ &= (Dc_k(\mathbf{Y}))' \end{aligned}$$

So that

$$\frac{\partial c_k}{\partial Y} = (2|\lambda_k^*|) \text{sgn}(\lambda_k^*) \mathbf{L}_k \mathbf{Y} \mathbf{\Pi}_k \mathbf{u}_k \mathbf{u}'_k \mathbf{\Pi}'_k$$

The proposition then follows by removing the absolute value and multiplication by the sign. \square

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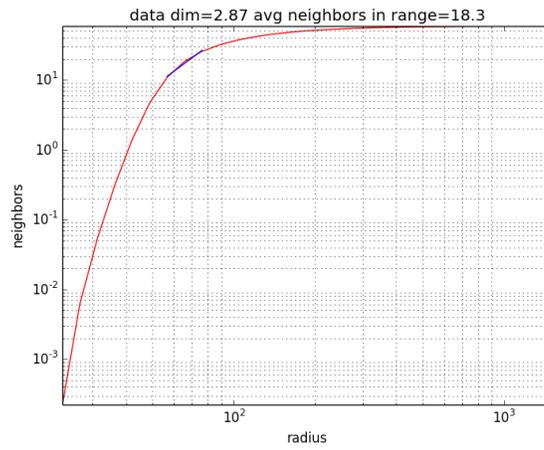


Figure 1: The average number of neighbors $m(r)$ vs the neighborhood radius r , on a log-log scale, for the SDSS spectra data, computed on the whole sample of 675,000 galaxies. The blue regression line, is fitted to the graph points in the shown r range, and has slope 2.87. The absence of a linear region on this graph suggests that the data dimension varies with the scale. The analysis and visualization in this paper corresponds to the largest meaningful scale.