Supplementary material 6 410

Animal ethics statement 411 6.1

All experiments on animals were conducted with approval of the Animal Care and Use Committee of 412 the University of California, Berkeley. 413

6.2 Compute 414

All computational procedures were performed either on a desktop workstation running Ubuntu 18.04 415 with an Intel Xeon E5-2620 v4 CPU, four GTX 1080 Ti GPUs, and 112GB RAM, or on the Axon 416 computer cluster based at [redacted for anonymity] using nodes comprised of two Xeon E5-2660 v4 417 CPUs, eight GTX 1080 Ti GPUs, and 125GB RAM.

418

6.3 Broader societal impact 419

Our work is significant for interventional approaches to studying the brain and its connection 420 to disease. By minimising off-target activation, Bayesian target optimisation could enable (e.g.) 421 more precise synaptic connectivity mapping, improving our understanding of neural circuitry. This 422 423 advancement has potential implications for understanding brain disorders like epilepsy, where abnormal synaptic connections are central to seizure generation and propagation. Deepening our 424 understanding of these diseases can lead to enhanced targeted interventions and more effective 425 therapeutic strategies, benefiting individuals with neurological disorders. 426

6.4 Code availability 427

An open-source implementation of Bayesian target optimisation is available in Python at https: 428 //anonymous.4open.science/r/bataro-4401/. 429

Single-target holographic stimulus optimisation with posterior uncertainty 6.5 430

Here we provide further mathematical details for optimising holographic stimuli. First, we develop 431 the approach for single optogenetic targets, as this is most closely related to existing GP-based 432 receptive field inference techniques. The single-target case also allows us to have a full treatment 433 of posterior uncertainty (unlike for optimising ensemble stimuli) which may be desired in certain 434 applications. 435

Optogenetic receptive field model. We use a GP-Bernoulli approach to model the response y_{nt} of 436 neuron n on trial t to a single-target stimulus \mathbf{x}_t , 437

$$y_{nt} \sim \text{Bernoulli}(\sigma(g_n(\mathbf{x}_t))),$$
 (9)

where the stimulus $\mathbf{x}_t = (c_{1t}, c_{2t}, I_t) \in \mathbb{R}^3$ represents the two-dimensional coordinates and laser 438 power of the t-th hologram. Each ORF follows a three-dimensional GP prior $g_n \sim \mathcal{GP}(m_n(\cdot), k(\cdot, \cdot))$, 439 where m_n and k again are the mean and covariance functions of the GP. 440

Posterior inference. Unlike for ensemble stimulation, for single-target stimulation we do not require 441 442 that the ORF q_n is non-negative. Consequently, the posterior of q_n is a GP, which allows us to work with a full description of posterior uncertainty. To compute the posterior, we use the conventional 443 Laplace approximation. Briefly, this consists of approximating the posterior using a multivariate 444 normal $q(g_n \mid \boldsymbol{\mu}_n, \boldsymbol{\Sigma}_n) = \text{Normal}(g_n \mid \boldsymbol{\mu}_n, \boldsymbol{\Sigma}_n) \approx p(g_n \mid \mathbf{y}_n, \mathbf{X}, \phi)$. The mean $\boldsymbol{\mu}_n$ is obtained by 445 maximising the log-posterior, given by the expression 446

$$\ln p(g_n \mid \mathbf{y}_n, \mathbf{X}, \phi) = \sum_{t=1}^T \ln p(\mathbf{y}_{nt} \mid \mathbf{x}_t, g_n) + \ln p(g_n(\mathbf{x}_1), \dots, g_n(\mathbf{x}_T) \mid \phi) + \text{const}, \quad (10)$$

where $\mathbf{X} = (\mathbf{x}_1, \dots, \mathbf{x}_T)$ and where const does not depend on g_n . Since the posterior is log-concave 447 in g_n , we use Newton's method to identify the global optimum of Equation 10, and adaptively set the 448 Newton step-size using a standard backtracking line-search method. Letting $\mathbf{H} = \nabla \nabla_{q_n} \ln p(q_n)$ 449 $\mathbf{y}_n, \mathbf{X}, \phi$) be the Hessian of the log-posterior, the posterior covariance matrix is obtained by setting 450 $\Sigma_n = -\mathbf{H}^{-1} \mid_{g_n = \mu_n}.$ 451

Target optimisation. Let $G = (g_1, \ldots, g_N)$, and define the predicted evoked activity for single holographic targets as $\hat{y}(\mathbf{x}, G) = (\sigma(g_1(\mathbf{x})), \ldots, \sigma(g_N(\mathbf{x})))$. To minimise the error between a target binary activity pattern $\mathbf{\Omega} \in \{0, 1\}^N$ and the predicted evoked activity, we solve an optimisation problem that accounts for the uncertainty in the ORF estimates:

$$\mathbf{x}_{\text{optimal}} = \underset{\mathbf{x}}{\operatorname{argmin}} \mathbb{E}_{q(G|\boldsymbol{\mu},\boldsymbol{\Sigma})} \left[\| \boldsymbol{\Omega} - \hat{y}(\mathbf{x},G) \|^2 \right] \quad \text{such that} \quad 0 \le I \le I_{\max},$$
(11)

where $q(G \mid \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \prod_{n=1}^{N} q(g_n \mid \boldsymbol{\mu}_n, \boldsymbol{\Sigma}_n)$ gives the joint posterior across all ORFs. To solve Equation 11] we first sample ORFs $g_n^{(s)}$ (for s = 1, ..., S) from their posterior distributions to approximate the expected error at the current estimate \mathbf{x}^* ,

$$\mathbb{E}_{q(G|\boldsymbol{\mu},\boldsymbol{\Sigma})}\left[\left\|\boldsymbol{\Omega}-\hat{y}(\mathbf{x}^*,G)\right\|^2\right] \approx \frac{1}{S} \sum_{s=1}^{S} \sum_{n=1}^{N} \left(\Omega_n - \sigma(g_n^{(s)}(\mathbf{x}^*))\right)^2.$$
(12)

Then, we compute the partial derivative (in dimension *d*) of the expected error by differentiating through the Monte Carlo approximation,

$$\frac{\partial}{\partial x_d^*} \mathbb{E}_{q(G|\boldsymbol{\mu},\boldsymbol{\Sigma})} \left[\|\boldsymbol{\Omega} - \hat{y}(\mathbf{x}^*,G)\|^2 \right] \approx -\frac{2}{S} \sum_{s=1}^S \sum_{n=1}^N (\Omega_n - \sigma(g_n^{(s)}(\mathbf{x}^*))\sigma'(g_n^{(s)}(\mathbf{x}^*)) \frac{\partial}{\partial x_d^*} g_n^{(s)}(\mathbf{x}^*).$$
(13)

Next we must evaluate the partial derivative on the right-hand side of Equation 13. We use the fact
that a GP and its derivative are jointly GP-distributed, and hence infer the derivative from observations
of the ORF. The covariance between a GP and its derivative is given by [40, Sec 9.4]

⁴⁶³ Of the OKF. The covariance between a OF and its derivative is given by

$$\operatorname{cov}\left(g_n(\mathbf{x}_t), \frac{\partial}{\partial x_d^*} g_n(\mathbf{x}^*)\right) = \frac{\partial k(\mathbf{x}_t, \mathbf{x}^*)}{\partial x_d^*} = \frac{\alpha^2}{\lambda_d^2} (x_{dt} - x_d^*) \exp\left(-\frac{\|\mathbf{x}_t - \mathbf{x}^*\|^2}{2\lambda_d^2}\right), \quad (14)$$

where the second equality is specific to the RBF covariance. Thus, we can use Equation 14 to obtain the posterior predictive mean for the derivative GPs in closed form as [46, Sec 2.7]

$$\mathbb{E}_{q(g_n|\boldsymbol{\mu}_n,\boldsymbol{\Sigma}_n)}\left[\frac{\partial g_n(\mathbf{x}^*)}{\partial x_d^*}\right] = \frac{\partial m_n(\mathbf{x}^*)}{\partial x_d^*} + \operatorname{cov}\left(g_n(\mathbf{X}), \frac{\partial g_n(\mathbf{x}^*)}{\partial x_d^*}\right)^\top \mathbf{K}^{-1}(\boldsymbol{\mu}_n - m_n(\mathbf{X})).$$
(15)

Here $\mathbf{X} = (\mathbf{x}_1, \dots, \mathbf{x}_T)$ is the collection of unique points on the ORF probed during calibration. If Equation 15 is combined with an expression for the posterior predictive variance, one obtains a full predictive distribution over derivative functions consistent with the observed neural responses. However, rather than working with this full distribution, we instead use Equation 15 to approximate the derivatives of the Monte Carlo samples by replacing the posterior mean μ_n with a Monte Carlo sample,

$$\frac{\partial g_n^{(s)}(\mathbf{x}^*)}{\partial x_d^*} \approx \frac{\partial m_n(\mathbf{x}^*)}{\partial x_d^*} + \operatorname{cov}\left(g_n(\mathbf{X}), \frac{\partial g_n(\mathbf{x}^*)}{\partial x_d^*}\right)^\top \mathbf{K}^{-1}(g_n^{(s)}(\mathbf{X}) - m_n(\mathbf{X})).$$
(16)

Equation 16 then allows us to define a closed-form approximate gradient $\tilde{\nabla}_{\mathbf{x}^*} g_n^{(s)}$ at test point \mathbf{x}^* , defined as

$$\tilde{\nabla}_{\mathbf{x}^*} g_n^{(s)} = \left[\frac{\partial g_n^{(s)}(\mathbf{x}^*)}{\partial x_1^*}, \dots, \frac{\partial g_n^{(s)}(\mathbf{x}^*)}{\partial x_D^*} \right]^\top,$$
(17)

which we use in the single-target projected gradient descent algorithm (Algorithm 2). Note that one
could also consider a quadrature approach to solving Equation 12, which may be more efficient than
Monte Carlo sampling. However, the presentation of the Monte Carlo approach is instructive for
deriving the optimisation of ensemble stimuli below.

478 6.6 Additional details on ensemble stimulus optimisation approach

The approach for optimising holographic ensemble stimuli is based on the approach for single-target optimisation, but modified to account for differences in the ORF model and inference. In particular, we again seek to minimise the error between a target activity pattern Ω and the predicted evoked Algorithm 2: Projected Monte Carlo gradient descent algorithm for optimising single-target holograms

- 1 Infer ORF posterior $q(G \mid \boldsymbol{\mu}, \boldsymbol{\Sigma})$ from calibration data $\{\mathbf{y}_n\}_{n=1}^N$, **X** using the Laplace approximation.
- 2 Precompute the negative of the Hessian $\mathbf{W}_n = -\nabla \nabla \ln p(\mathbf{y}_n \mid \mathbf{X}, g_n) \mid_{g_n = \mu_n}$ for each *n*. 3 Initialise **x** to random location near soma of target neuron and with random laser power.
- 4 while target not converged do
- for n = 1, ..., N do 5 Compute mean and variance of posterior predictive distribution at current target estimate 6 \mathbf{x} via $\mu_n(\mathbf{x}) = m_n(\mathbf{x}) + k(\mathbf{X}, \mathbf{x})^\top \mathbf{K}^{-1}(\boldsymbol{\mu}_n - m_n(\mathbf{X}))$, and $\sigma_n^2(\mathbf{x}) = k(\mathbf{x}, \mathbf{x}) - k(\mathbf{X}, \mathbf{x})^\top (\mathbf{K} + \mathbf{W}_n^{-1})^{-1} k(\mathbf{X}, \mathbf{x})$. Sample ORFs at the current target estimate, $g_n^{(s)}(\mathbf{x}) \sim \operatorname{Normal}(\mu_n(\mathbf{x}), \sigma_n^2(\mathbf{x}))$ for 7 $s=1,\ldots,S.$ Construct approximate gradients $\tilde{\nabla}_{\mathbf{x}} g_n^{(s)}$ for $s = 1, \dots, S$ using Equation 17 8 end 9 Set $\delta_{\mathbf{x}} = -\frac{2}{S} \sum_{s=1}^{S} \sum_{n=1}^{N} (\Omega_n - \sigma(g_n^{(s)}(\mathbf{x})) \sigma'(g_n^{(s)}(\mathbf{x})) \tilde{\nabla}_{\mathbf{x}} g_n^{(s)}(\mathbf{x})$ as per Equation 13 Perform gradient descent update, $\mathbf{x} \leftarrow \mathbf{x} + \beta \delta_{\mathbf{x}}$ with step-size β . 10 11 Project laser power onto feasible domain, $I \leftarrow \min(I, I_{\max})$ 12 13 end

activity, but now using the MAP estimates $\mathcal{G} = \{\hat{g}_n, \hat{\theta}_n\}_{n=1}^N$ in place of the full posterior distributions. 482 Let $\hat{y}(\mathbf{x}, \mathcal{G}) = (\sigma(\hat{\gamma}_1(\mathbf{x}) - \hat{\theta}_1), \dots, \sigma(\hat{\gamma}_N(\mathbf{x}) - \hat{\theta}_N))$ be the predicted population response to an ensemble stimulus, where $\hat{\gamma}_n(\mathbf{x}) = \sum_{j=1}^J \hat{g}_n(\mathbf{x}^j)$. The optimal ensemble stimulus is now 483 484

$$\mathbf{x}_{\text{optimal}} = \underset{\mathbf{x}}{\operatorname{argmin}} \|\mathbf{\Omega} - \hat{y}(\mathbf{x}, \mathcal{G})\|^2 = \underset{\mathbf{x}}{\operatorname{argmin}} \sum_{n=1}^{N} \left(\Omega_n - \sigma(\hat{\gamma}_n(\mathbf{x}) - \hat{\theta}_n)\right)^2$$
(18)

such that $0 \le I \le I_{\text{max}}$. Evaluating the partial derivative of Equation 18 with respect to dimension d 485 of a test point x^* yields, 486

$$\frac{\partial}{\partial x_d^*} \|\mathbf{\Omega} - \hat{y}(\mathbf{x}^*, \mathcal{G})\|^2 = -2\sum_{n=1}^N (\Omega_n - \sigma(\hat{\gamma}_n(\mathbf{x}^*) - \hat{\theta}_n))\sigma'(\hat{\gamma}_n(\mathbf{x}^*) - \hat{\theta}_n)\frac{\partial}{\partial x_d^*}\hat{\gamma}_n(\mathbf{x}^*).$$
(19)

The derivative on the right-hand side of Equation 19 is given by $\frac{\partial}{\partial x_d^*} \hat{\gamma}_n(\mathbf{x}) = \sum_{j=1}^J \frac{\partial}{\partial x_d^*} \hat{g}_n(\mathbf{x}^j)$, 487 which requires computing the derivative of $\hat{g}_n(\mathbf{x}^j)$. To evaluate this derivative, we use a similar trick 488 to Equation 16, but substituting the MAP estimate in place of the posterior mean or Monte Carlo 489 sample, 490

$$\frac{\partial}{\partial x_d^*} \hat{g}_n(\mathbf{x}^*) = \frac{\partial}{\partial x_d^*} m_n(\mathbf{x}^*) + \operatorname{cov}\left(g_n(\mathbf{X}), \frac{\partial}{\partial x_d^*} g_n(\mathbf{x}^*)\right)^\top \mathbf{K}^{-1}(\hat{g}_n(\mathbf{X}) - m_n(\mathbf{X})).$$
(20)

This expression can also be arrived at by first evaluating the posterior predictive mean of $g_n(\mathbf{x}^*)$, and 491 then differentiating with respect to x_d^* . 492

We use Equation 20 to define a closed-form gradient $\nabla_{\mathbf{x}^*} \hat{\gamma}_n$ at test point \mathbf{x}^* via 493

$$\nabla_{\mathbf{x}^*} \hat{\gamma}_n = \left[\frac{\partial \hat{\gamma}_n(\mathbf{x}^*)}{\partial x_1^*}, \dots, \frac{\partial \hat{\gamma}_n(\mathbf{x}^*)}{\partial x_D^*} \right]^\top.$$
(21)

Finally, Equation 21 is used in the projected gradient descent algorithm for optimising ensemble 494 stimuli (Algorithm 1). 495

6.7 Further details on simulations and "synthetic" optogenetics experiments 496

Simulations consisted of both ORF mapping and stimulus optimisation phases. ORF mapping 497 required probing responses to stimulation at a range of laser powers and stimulus locations. We 498



Figure S1: Effect of reducing the number of points at which each ORF is probed. (a) In the high coverage case (left), each ORF is probed by stimulating at a 5×5 grid of points near the soma (grid points separated by 10 μ m), at three different laser powers. In the low coverage case (right), this reduces to stimulating at just a 3×3 grid (grid points separated by 12 μ m) at three powers. However, as the density of opsin-expressing neurons increases, ORFs are probed at high density even in the low coverage case as the grids from different neurons increasingly overlap. (b) Minimal performance difference between the high and low coverage cases in simulations with 50 neurons. (c) Reduction in optical write-in error using cell-attached recordings as in Figure 4, but with low coverage. Reduction in average write-in error, 74% (c.f. 85% with high coverage, Figure 4c).

defined a grid of stimulation points surrounding each neuron. In the spatial dimensions, the grid 499 ranged from $-20 \ \mu m$ to 20 $\ \mu m$ relative to the centroid of the neuron in steps of 10 $\ \mu m$, and powers 500 ranged from 30 mW to 70 mW in steps of 20 mW. The complete grid was thus given by the Cartesian 501 product $\{-20, -10, 0, 10, 20\} \times \{-20, -10, 0, 10, 20\} \times \{30, 50, 70\}$. For opsin-expressing neurons 502 that were spaced far apart, this coarse-resolution grid was sufficient because risk of OTS was low, 503 and therefore ORF mapping was not needed at high detail. On the other hand, as the density of 504 opsin-expressing neurons increased, the grids surrounding each neuron increasingly overlapped with 505 each other, resulting in much denser sampling of the ORFs. 506

For the synthetic optogenetics experiments (based on the cell-attached recordings), we used the same 507 spatial grid spacing but used laser powers of 10, 25, and 40 mW to match the range of powers used 508 in the underlying slice experiment, though note that the slice experiment had a denser spacing than 509 our chosen 15 mW (see example loose-patch recordings below), which we chose to reduce the ORF 510 mapping time. For the optogenetics experiments involving three spatial dimensions, we extended 511 the grid sampling to include depths of $-60 \ \mu m$ to $60 \ \mu m$ in steps of $30 \ \mu m$. We also explored the 512 effect of reducing the number of probed grid points to further reduce the time spent mapping ORFs, 513 and found that Bayesian target optimisation maintained high performance when probing with a 3×3 514 515 spatial grid of $\{-12, 0, 12\} \times \{-12, 0, 12\}$ (Figure S1).

We selected the parameters of the GP covariance kernel using 5-fold cross-validation on a separate set 516 of recordings that were made on the same set of four cells, ensuring the hyperparameter selection was 517 using out-of-sample data. Cross-validation was performed using a grid search over a set of possible 518 hyperparameters: the possible radial lengthscales were 2, 4, 8, 16, the power lengthscales were 2, 519 4, 8, 16, and the amplitudes were 1, 2, 4, 8, 16. For each hyperparameter combination θ and for 520 each cell, we used Newton's method to fit the GP-Bernoulli model to 80% of the trials in the loose-521 patch data, yielding an ORF estimate \hat{g}_{θ} . On the remaining 20% of the trials (denoted as $\mathcal{T}_{held-out}$), 522 we evaluated the log-likelihood, $\sum_{t \in \mathcal{T}_{held-out}} \{y_t \ln(\sigma(\hat{g}_{\theta}(\mathbf{x}_t))) + (1 - y_t) \ln(1 - \sigma(\hat{g}_{\theta}(\mathbf{x}_t)))\}\}$. We averaged the log-likelihood across all five folds and across all four cells, and chose the hyperparameter 523 524 combination θ that yielded the largest average log-likelihood, resulting in a radial lengthscale of 8, a 525 power lengthscale of 16, and a kernel amplitude of 8. 526

The GP parameters for generating the simulations in Figure 3 inferring the resulting ORFs, and generating synthetic optogenetics experiments with two and three spatial dimensions are given in Table S1 For reference, a typical ORF mean function is given in Figure S2



Figure S2: Example mean function (shown at three powers) used for simulations (left column). Also shown are four samples from the ORF prior corresponding to this mean function (right four columns). Parameters given in Table S1.

Parameter	Symbol	Value
Simulations (data generation)		
Mean function excitability	ρ	0.125
Mean function width	σ_m^2	$3 imes 10^2 \ \mu { m m}$
Spike threshold	θ	3.5
Kernel radial lengthscale	λ_s	$8 \ \mu m$
Kernel power lengthscale	λ_I	20 mW
Kernel amplitude	α^2	0.2
Kernel marginal variance	σ_d^2	10^{-5}
Simultaneously stimulated neurons during ORF mapping	J	10
Simulations (ORF inference)		
Mean function excitability	ho	0.125
Mean function width	σ_m^2	$3 imes 10^2 \ \mu { m m}$
Kernel radial lengthscale	λ_s	$5 \ \mu m$
Kernel power lengthscale	λ_I	16 mW
Kernel amplitude	α^2	1
Kernel marginal variance	σ_d^2	10^{-5}
Learning rate for spike thresholds $(\{\theta_n\}_{n=1}^N)$	—	5
Number of random initialisations	—	5
Synthetic optogenetics experiments (two spatial dimensions)		
Mean function excitability	ρ	0.175
Mean function width	σ_m^2	$3 imes 10^2 \ \mu { m m}$
Kernel radial lengthscale	λ_s	$8 \ \mu m$
Kernel power lengthscale	λ_I	16 mW
Kernel amplitude	α^2	8
Kernel marginal variance	σ_d^2	10^{-5}
Learning rate for spike thresholds $(\{\theta_n\}_{n=1}^N)$	—	5
Number of random initialisations	—	5
Synthetic optogenetics experiments (three spatial dimensions)		
Mean function excitability	ρ	0.175
Mean function width (x/y dimensions)	σ_m^2	$3 imes 10^2 \ \mu { m m}$
Mean function width (z dimension)	—	$3 \times 10^3 \ \mu { m m}$
Kernel radial lengthscale (x/y dimensions)	λ_s	$8 \ \mu m$
Kernel axial lengthscale (z dimension)	λ_z	$32 \ \mu m$
Kernel power lengthscale	λ_I	16 mW
Kernel amplitude	α^2	8
Kernel marginal variance	σ_d^2	10^{-5}
Learning rate for spike thresholds $(\{\theta_n\}_{n=1}^N)$	_	5
Number of random initialisations	_	5

Table S1: Parameters used for simulations and generating synthetic optogenetics experiments.

530 6.8 Additional examples of optogenetic receptive fields from cell-attached recordings

Figures S3 to S6 show examples of four ORFs that have been comprehensively mapped using twophoton optogenetic stimulation and cell-attached recordings of evoked spikes. Note the unpredictable differences in ORF shape across laser powers and depths, motivating a nonparametric approach.



Figure S3: Loose-patch recording and inferred ORF (experiment 1/4).



Figure S4: Loose-patch recording and inferred ORF (experiment 2/4)



Figure S5: Loose-patch recording and inferred ORF (experiment 3/4)



Figure S6: Loose-patch recording and inferred ORF (experiment 4/4)