

6 Supplemental Materials: Mathematical Proofs

This section shows the detailed proofs to the proposed theorems.

6.1 Basic Lemmas

The following lemma reveals the fact that the isomeric property is related to the invertibility of the sub-matrices of a basis matrix.

Lemma 6.1. *Let $\Omega \subseteq \{1, 2, \dots, m\} \times \{1, 2, \dots, n\}$ and $U_0 \in \mathbb{R}^{m \times r}$ be the basis matrix of a subspace embedded in \mathbb{R}^m . Denote the i th row of U_0 as u_i^T , i.e., $U_0 = [u_1^T; u_2^T; \dots; u_m^T]$. Define δ_{ij} as*

$$\delta_{ij} = \begin{cases} 1, & \text{if } (i, j) \in \Omega, \\ 0, & \text{otherwise.} \end{cases} \quad (10)$$

Then the matrices, $\sum_{i=1}^m \delta_{ij} u_i u_i^T$, $\forall 1 \leq j \leq n$, are all invertible if and only if U_0 is Ω -isomeric.

Proof. Note that

$$([U_0]_{\Omega^j, :})^T ([U_0]_{\Omega^j, :}) = [\delta_{1j} u_1, \delta_{2j} u_2, \dots, \delta_{mj} u_m] \begin{bmatrix} \delta_{1j} u_1^T \\ \delta_{2j} u_2^T \\ \vdots \\ \delta_{mj} u_m^T \end{bmatrix} = \sum_{i=1}^m (\delta_{ij})^2 u_i u_i^T = \sum_{i=1}^m \delta_{ij} u_i u_i^T.$$

Now, it is easy to see that $\sum_{i=1}^m \delta_{ij} u_i u_i^T$ is invertible is equivalent to that $([U_0]_{\Omega^j, :})^T ([U_0]_{\Omega^j, :})$ is positive definite, which is further equivalent to that $\text{rank}([U_0]_{\Omega^j, :}) = \text{rank}(U_0)$, $\forall j = 1, \dots, n$. \square

The next lemma will be used multiple times in the proof.

Lemma 6.2. *Let $\Omega \subseteq \{1, 2, \dots, m\} \times \{1, 2, \dots, n\}$ and \mathcal{P} be an orthogonal projection onto some subspace of $\mathbb{R}^{m \times n}$. If $\|\mathcal{P} \mathcal{P}_\Omega^\perp \mathcal{P}\| < 1$ then $\mathcal{P} \mathcal{P}_\Omega \mathcal{P}$ is an invertible operator.*

Proof. Provided that $\|\mathcal{P} \mathcal{P}_\Omega^\perp \mathcal{P}\| < 1$, $\mathcal{I} + \sum_{i=1}^\infty (\mathcal{P} \mathcal{P}_\Omega^\perp \mathcal{P})^i$ is well defined. Also, notice that

$$\mathcal{P} \mathcal{P}_\Omega \mathcal{P} = \mathcal{P}(\mathcal{I} - \mathcal{P}_\Omega^\perp) \mathcal{P} = \mathcal{P}(\mathcal{I} - \mathcal{P} \mathcal{P}_\Omega^\perp \mathcal{P}).$$

Thus, for any $M \in \mathcal{P}$, the following holds:

$$\begin{aligned} & \mathcal{P} \mathcal{P}_\Omega \mathcal{P} (\mathcal{I} + \sum_{i=1}^\infty (\mathcal{P} \mathcal{P}_\Omega^\perp \mathcal{P})^i) (M) \\ &= \mathcal{P}(\mathcal{I} - \mathcal{P} \mathcal{P}_\Omega^\perp \mathcal{P}) (\mathcal{I} + \sum_{i=1}^\infty (\mathcal{P} \mathcal{P}_\Omega^\perp \mathcal{P})^i) (M) \\ &= \mathcal{P}(\mathcal{I} + \sum_{i=1}^\infty (\mathcal{P} \mathcal{P}_\Omega^\perp \mathcal{P})^i - \mathcal{P} \mathcal{P}_\Omega^\perp \mathcal{P} - \sum_{i=2}^\infty (\mathcal{P} \mathcal{P}_\Omega^\perp \mathcal{P})^i) (M) \\ &= \mathcal{P}(M) = M. \end{aligned}$$

In a similar way, it could be also verified that $(\mathcal{I} + \sum_{i=1}^\infty (\mathcal{P} \mathcal{P}_\Omega^\perp \mathcal{P})^i) \mathcal{P} \mathcal{P}_\Omega \mathcal{P} (M) = M$. As a consequence, $\mathcal{I} + \sum_{i=1}^\infty (\mathcal{P} \mathcal{P}_\Omega^\perp \mathcal{P})^i$ is the inverse operator of $\mathcal{P} \mathcal{P}_\Omega \mathcal{P}$. \square

Lemma 6.3. *Let $\Omega \subseteq \{1, 2, \dots, m\} \times \{1, 2, \dots, n\}$ and \mathcal{P} be an orthogonal projection onto some subspace of $\mathbb{R}^{m \times n}$. If $\|\mathcal{P} \mathcal{P}_\Omega^\perp \mathcal{P}\| < 1$ then $\mathcal{P} \cap \mathcal{P}_\Omega^\perp = \{0\}$.*

Proof. Suppose that $M \in \mathcal{P} \cap \mathcal{P}_\Omega^\perp$, i.e., $M = \mathcal{P}(M) = \mathcal{P}_\Omega^\perp(M)$. Then we have $M = \mathcal{P} \mathcal{P}_\Omega^\perp \mathcal{P}(M)$ and thus

$$\|M\|_F = \|\mathcal{P} \mathcal{P}_\Omega^\perp \mathcal{P}(M)\|_F \leq \|\mathcal{P} \mathcal{P}_\Omega^\perp \mathcal{P}\| \|M\|_F \leq \|M\|_F.$$

Since $\|\mathcal{P} \mathcal{P}_\Omega^\perp \mathcal{P}\| < 1$, the last equality above can hold only when $M = 0$. \square

The following lemma is well-known.

Lemma 6.4 (Lemma 11 of [29]). *For any matrices M, N, W and Z of consistent sizes, we have that*

$$\left\| \begin{bmatrix} M & N \\ W & Z \end{bmatrix} \right\|_* \geq \|M\|_*,$$

where the equality can hold if and only if $N = 0$, $W = 0$ and $Z = 0$.

Proof. By Lemma 11 of [29],

$$\left\| \begin{bmatrix} M & N \\ W & Z \end{bmatrix} \right\|_* \geq \|[M, N]\|_* \geq \|M\|_*.$$

The validity of the first equality requires that $W = 0$ and $Z = 0$. The second equality demands $N = 0$. \square

6.2 Critical Lemmas

The following lemma (i.e., Theorem 3.1) has a critical role in the proof.

Lemma 6.5 (Theorem 3.1). *Let $L_0 \in \mathbb{R}^{m \times n}$ and $\Omega \subseteq \{1, 2, \dots, m\} \times \{1, 2, \dots, n\}$. Let the SVD of L_0 be $U_0 \Sigma_0 V_0^T$. Denote $\mathcal{P}_{U_0}(\cdot) = U_0 U_0^T(\cdot)$ and $\mathcal{P}_{V_0}(\cdot) = (\cdot) V_0 V_0^T$. Then we have the following:*

1. *The linear operator $\mathcal{P}_{U_0} \mathcal{P}_\Omega \mathcal{P}_{U_0}$ is invertible if and only if U_0 is Ω -isomeric.*
2. *The linear operator $\mathcal{P}_{V_0} \mathcal{P}_\Omega \mathcal{P}_{V_0}$ is invertible if and only if V_0 is Ω^T -isomeric.*

Proof. The above two claims are proved in the same way, and thereby we only present the proof to first one. Since the operator $\mathcal{P}_{U_0} \mathcal{P}_\Omega \mathcal{P}_{U_0}$ is linear and \mathcal{P}_{U_0} is a linear space of finite dimension, the sufficiency can be proved by showing that $\mathcal{P}_{U_0} \mathcal{P}_\Omega \mathcal{P}_{U_0}$ is an injection. That is, we need to prove that the following linear system has no nonzero solution:

$$\mathcal{P}_{U_0} \mathcal{P}_\Omega \mathcal{P}_{U_0}(M) = 0, \text{ s.t. } M \in \mathcal{P}_{U_0}.$$

Assume that $\mathcal{P}_{U_0} \mathcal{P}_\Omega \mathcal{P}_{U_0}(M) = 0$. Then we have

$$U_0^T \mathcal{P}_\Omega (U_0 U_0^T M) = 0.$$

Denote the i th row and j th column of U_0 and $U_0^T M$ as u_i^T and b_j , respectively. That is, $U_0 = [u_1^T; u_2^T; \dots; u_m^T]$ and $U_0^T M = [b_1, b_2, \dots, b_n]$. Define δ_{ij} as in (10). Then the j th column of $U_0^T \mathcal{P}_\Omega (U_0 U_0^T M)$ is given by

$$U_0^T \begin{bmatrix} \delta_{1j} u_1^T b_j \\ \delta_{2j} u_2^T b_j \\ \vdots \\ \delta_{mj} u_m^T b_j \end{bmatrix} = \left(\sum_{i=1}^m \delta_{ij} u_i u_i^T \right) b_j.$$

By Lemma 6.1, the matrix $\sum_{i=1}^m \delta_{ij} u_i u_i^T$ is invertible. Hence, $U_0^T \mathcal{P}_\Omega (U_0 U_0^T M) = 0$ implies that

$$b_j = 0, \forall j = 1, \dots, n,$$

i.e., $U_0^T M = 0$. By the assumption of $M \in \mathcal{P}_{U_0}$, $M = 0$.

It remains to prove the necessity. Assume that U_0 is not Ω -isomeric. By Lemma 6.1, there exists j such that the matrix $\sum_{i=1}^m \delta_{ij} u_i u_i^T$ is singular and therefore has a nonzero null space. So, there exists $M_1 \neq 0$ such that $U_0^T \mathcal{P}_\Omega (U_0 M_1) = 0$. Let $M = U_0 M_1$. Then we have $M \neq 0$, $M \in \mathcal{P}_{U_0}$ and

$$\mathcal{P}_{U_0} \mathcal{P}_\Omega \mathcal{P}_{U_0}(M) = 0.$$

This contradicts the assumption that $\mathcal{P}_{U_0} \mathcal{P}_\Omega \mathcal{P}_{U_0}$ is invertible. As a consequence, U_0 must be Ω -isomeric. \square

By Lemma 6.2, $\|\mathcal{P}_{U_0} \mathcal{P}_\Omega^\perp \mathcal{P}_{U_0}\| < 1$ also leads to the invertibility of $\mathcal{P}_{U_0} \mathcal{P}_\Omega \mathcal{P}_{U_0}$. So, according to Lemma 6.5, $\|\mathcal{P}_{U_0} \mathcal{P}_\Omega^\perp \mathcal{P}_{U_0}\| < 1$ should be related to the isomeric property. This is true, as shown in the following lemma.

Lemma 6.6. Let $L_0 \in \mathbb{R}^{m \times n}$ and $\Omega \subseteq \{1, 2, \dots, m\} \times \{1, 2, \dots, n\}$. Let the SVD of L_0 be $U_0 \Sigma_0 V_0^T$. Denote $\mathcal{P}_{U_0}(\cdot) = U_0 U_0^T(\cdot)$ and $\mathcal{P}_{V_0}(\cdot) = (\cdot) V_0 V_0^T$. Then we have the following:

1. $\|\mathcal{P}_{U_0} \mathcal{P}_\Omega^\perp \mathcal{P}_{U_0}\| < 1$ if and only if U_0 is Ω -isomeric.
2. $\|\mathcal{P}_{V_0} \mathcal{P}_\Omega^\perp \mathcal{P}_{V_0}\| < 1$ if and only if V_0 is Ω^T -isomeric.

Proof. The necessity could be proved by Lemma 6.2 and Lemma 6.5, and thereby we only need to prove the sufficiency. Denote δ_{ij} as in (10) and define a diagonal matrix D_j as $D_j = \text{diag}(\delta_{1j}, \delta_{2j}, \dots, \delta_{mj}) \in \mathbb{R}^{m \times m}$. Then we have

$$([U_0]_{\Omega^j, :})^T ([U_0]_{\Omega^j, :}) = U_0^T D_j^T D_j U_0 = U_0^T D_j U_0.$$

By Lemma 6.1, $U_0^T D_j U_0$ is positive definite and therefore has positive singular values. Also, we have $\|U_0^T D_j U_0\| \leq \|D_j\| \leq 1$. As a consequence,

$$\sigma_j \mathbf{I} \preceq U_0^T D_j U_0 \preceq \mathbf{I},$$

where $\sigma_j > 0$ is the minimal singular value of $U_0^T D_j U_0$. Denote the j th column of $\mathcal{P}_{U_0}(M)$ as b_j . Then we have

$$\begin{aligned} \|[\mathcal{P}_{U_0} \mathcal{P}_\Omega^\perp \mathcal{P}_{U_0}(M)]_{:,j}\|_2 &= \|U_0 U_0^T b_j - U_0 (U_0^T D_j U_0) U_0^T b_j\|_2 \\ &= \|(\mathbf{I} - U_0^T D_j U_0) U_0^T b_j\|_2 \leq \|(\mathbf{I} - U_0^T D_j U_0)\| \|U_0^T b_j\|_2 \\ &= (1 - \sigma_j) \|U_0^T b_j\|_2 = (1 - \sigma_j) \|b_j\|_2, \forall j = 1, \dots, n, \end{aligned}$$

which implies that

$$\begin{aligned} \|\mathcal{P}_{U_0} \mathcal{P}_\Omega^\perp \mathcal{P}_{U_0}(M)\|_F^2 &\leq \sum_{j=1}^n (1 - \sigma_j)^2 \|b_j\|_2^2 \\ &\leq (1 - \sigma_{\min})^2 \|\mathcal{P}_{U_0}(M)\|_F^2, \end{aligned}$$

where $\sigma_{\min} = \min_j \{\sigma_j\} > 0$. Hence,

$$\|\mathcal{P}_{U_0} \mathcal{P}_\Omega^\perp \mathcal{P}_{U_0}\| \leq 1 - \sigma_{\min} < 1.$$

□

Lemma 6.5 and Lemma 6.6 imply that $\|\mathcal{P}_{U_0} \mathcal{P}_\Omega^\perp \mathcal{P}_{U_0}\| < 1$ is a sufficient and necessary condition for $\mathcal{P}_{U_0} \mathcal{P}_\Omega \mathcal{P}_{U_0}$ to be invertible. In fact, this is true for any orthogonal projections, as stated in the following lemma.

Lemma 6.7. Let $\Omega \subseteq \{1, 2, \dots, m\} \times \{1, 2, \dots, n\}$ and \mathcal{P} be an orthogonal projection onto some r -dimensional subspace of $\mathbb{R}^{m \times n}$. Then the linear operator, $\mathcal{P} \mathcal{P}_\Omega \mathcal{P}$, is an invertible operator if and only if $\|\mathcal{P} \mathcal{P}_\Omega^\perp \mathcal{P}\| < 1$.

Proof. The sufficiency has been proven by Lemma 6.2, and thus we only need to prove that $\|\mathcal{P} \mathcal{P}_\Omega^\perp \mathcal{P}\| < 1$ is necessary. Let $\text{vec}(\cdot)$ denote the vectorization of a matrix formed by stacking the columns of the matrix into a single column vector. Suppose that the basis matrix associated with the operator \mathcal{P} is given by $P \in \mathbb{R}^{mn \times r}$, $P^T P = \mathbf{I}$; namely,

$$\text{vec}(\mathcal{P}(M)) = P P^T \text{vec}(M), \forall M \in \mathbb{R}^{m \times n}.$$

Denote δ_{ij} as in (10) and define a diagonal matrix D as

$$D = \text{diag}(\delta_{11}, \delta_{21}, \dots, \delta_{ij}, \dots, \delta_{mn}) \in \mathbb{R}^{mn \times mn}.$$

Notice that

$$\begin{aligned} \mathcal{P}(M) &= \mathcal{P} \left(\sum_{i=1}^m \sum_{j=1}^n \langle M, e_i e_j^T \rangle e_i e_j^T \right) \\ &= \sum_{i=1}^m \sum_{j=1}^n \langle M, e_i e_j^T \rangle \mathcal{P}(e_i e_j^T), \end{aligned}$$

where e_i is the i th standard basis and $\langle \cdot \rangle$ denotes the inner product between two matrices. With this notation, it is easy to see that

$$[\text{vec}(\mathcal{P}(e_1 e_1^T)), \text{vec}(\mathcal{P}(e_2 e_1^T)), \dots, \text{vec}(\mathcal{P}(e_m e_n^T))] = PP^T.$$

Similarly, we have

$$\mathcal{P}\mathcal{P}_\Omega\mathcal{P}(M) = \sum_{i=1}^m \sum_{j=1}^n \langle \mathcal{P}(M), e_i e_j^T \rangle (\delta_{ij} \mathcal{P}(e_i e_j^T)),$$

and thereby

$$\text{vec}(\mathcal{P}\mathcal{P}_\Omega\mathcal{P}(M)) = PP^T D P P^T \text{vec}(M).$$

For $\mathcal{P}\mathcal{P}_\Omega\mathcal{P}$ to be invertible, the matrix $P^T D P$ must be positive definite. To show this, let's assume that $P^T D P$ is singular. Then there exists a vector, $z \in \mathbb{R}^{mn}$, $z \neq 0$, that satisfies $P^T D P z = 0$. Let $\text{vec}(M) = Pz$. Then we have $PP^T D P P^T \text{vec}(M) = PP^T D P z = 0$. By $z \neq 0$, $\text{vec}(M) \neq 0$. Hence, there exists $M \in \mathcal{P}$ and $M \neq 0$ such that $\mathcal{P}\mathcal{P}_\Omega\mathcal{P}(M) = 0$. This contradicts the assumption that $\mathcal{P}\mathcal{P}_\Omega\mathcal{P}$ is invertible.

Denote the minimal singular value of $P^T D P$ as $\sigma_{\min} > 0$. Then we have

$$\begin{aligned} \|\mathcal{P}\mathcal{P}_\Omega^\perp\mathcal{P}(M)\|_F^2 &= \|\text{vec}(\mathcal{P}\mathcal{P}_\Omega^\perp\mathcal{P}(M))\|_2^2 \\ &= \|PP^T(\mathbf{I} - D)PP^T \text{vec}(M)\|_2^2 \\ &= \|(\mathbf{I} - P^T D P)P^T \text{vec}(M)\|_2^2 \\ &\leq (1 - \sigma_{\min})^2 \|P^T \text{vec}(M)\|_2^2 \\ &= (1 - \sigma_{\min})^2 \|\mathcal{P}(M)\|_F^2, \end{aligned}$$

which gives that $\|\mathcal{P}\mathcal{P}_\Omega^\perp\mathcal{P}\| \leq 1 - \sigma_{\min} < 1$. \square

The following lemma has been used in our discussions.

Lemma 6.8. *Let $\Omega \subseteq \{1, 2, \dots, m\} \times \{1, 2, \dots, n\}$ and \mathcal{P} be an orthogonal projection onto some subspace of $\mathbb{R}^{m \times n}$. Then the operator, $\mathcal{P}\mathcal{P}_\Omega\mathcal{P}$, is invertible if and only if $\mathcal{P} \cap \mathcal{P}_\Omega^\perp = \{0\}$.*

Proof. The necessity has been proven by Lemma 6.7 and Lemma 6.3. So, it suffices to prove that $\mathcal{P} \cap \mathcal{P}_\Omega^\perp = \{0\}$ can lead to the invertibility of the operator $\mathcal{P}\mathcal{P}_\Omega\mathcal{P}$. Consider a nonzero matrix $M \in \mathcal{P}$. Then we have

$$\|M\|_F^2 = \|\mathcal{P}(M)\|_F^2 = \|\mathcal{P}_\Omega\mathcal{P}(M) + \mathcal{P}_\Omega^\perp\mathcal{P}(M)\|_F^2 = \|\mathcal{P}_\Omega\mathcal{P}(M)\|_F^2 + \|\mathcal{P}_\Omega^\perp\mathcal{P}(M)\|_F^2,$$

which gives that

$$\|\mathcal{P}\mathcal{P}_\Omega^\perp\mathcal{P}(M)\|_F^2 \leq \|\mathcal{P}_\Omega^\perp\mathcal{P}(M)\|_F^2 = \|M\|_F^2 - \|\mathcal{P}_\Omega\mathcal{P}(M)\|_F^2.$$

By $\mathcal{P} \cap \mathcal{P}_\Omega^\perp = \{0\}$, $\mathcal{P}_\Omega\mathcal{P}(M) \neq 0$. Thus,

$$\|\mathcal{P}\mathcal{P}_\Omega^\perp\mathcal{P}\|^2 \leq 1 - \inf_{\|M\|_F=1} \|\mathcal{P}_\Omega\mathcal{P}(M)\|_F^2 < 1.$$

Again, by Lemma 6.7, the operator $\mathcal{P}\mathcal{P}_\Omega\mathcal{P}$ is invertible. \square

Consider a twinned problem of (7); namely,

$$\min_A \|A\|_*, \text{ s.t. } \mathcal{P}_\Omega(AX - L_0) = 0, \quad (11)$$

where $X \in \mathbb{R}^{p \times n}$ is supposed to be given. Similar to Theorem 3.4, we have the following lemma to guarantee the success of the above convex program.

Lemma 6.9. *Let $X \in \mathbb{R}^{p \times n}$ be a given matrix and $\Omega \subseteq \{1, 2, \dots, m\} \times \{1, 2, \dots, n\}$. If $L_0^T \in \text{span}\{X^T\}$ and X^T is Ω^T -isomeric then $A_0 = L_0 X^+$ is the unique minimizer to the problem in (11).*

Proof. Denote the SVDs of L_0 , X and L_0X^+ as $U_0\Sigma_0V_0^T$, $U_1\Sigma_1V_1^T$ and $U_2\Sigma_2V_2^T$, respectively. By $L_0^T \in \text{span}\{X^T\}$, $V_0 = V_1V_1^TV_0$ and thus

$$A_0X = L_0X^+X = L_0V_1V_1^T = L_0.$$

That is, $A_0 = L_0X^+$ is feasible to (11). By standard convexity arguments [30], $A_0 = L_0X^+$ is an optimal solution to the problem in (11) if there exists a matrix W (Lagrange multiplier) that obeys

$$\mathcal{P}_\Omega(W)X^T \in \partial\|L_0X^+\|_*,$$

where $\partial(\cdot)$ is the subgradient of a function. By Lemma 3.1, V_1 is Ω^T -isomeric. Then Lemma 6.5 gives that $\mathcal{P}_{V_1}\mathcal{P}_\Omega\mathcal{P}_{V_1}$ is an invertible operator. Hence, we could define W as

$$W = \mathcal{P}_{V_1}(\mathcal{P}_{V_1}\mathcal{P}_\Omega\mathcal{P}_{V_1})^{-1}(U_2V_2^T(X^T)^+).$$

With this notation, it can be calculated that

$$\begin{aligned} \mathcal{P}_\Omega(W)X^T &= \mathcal{P}_{V_1}\mathcal{P}_\Omega(W)X^T \\ &= \mathcal{P}_{V_1}\mathcal{P}_\Omega\mathcal{P}_{V_1}(\mathcal{P}_{V_1}\mathcal{P}_\Omega\mathcal{P}_{V_1})^{-1}(U_2V_2^T(X^T)^+)X^T \\ &= U_2V_2^T(X^T)^+X^T = U_2V_2^TU_1U_1^T. \end{aligned}$$

Since $(L_0X^+)^T \in \text{span}\{X\}$, we have

$$V_2^TU_1U_1^T = V_2^T, \text{ i.e., } V_2 \subseteq U_1.$$

As a result,

$$\mathcal{P}_\Omega(W)X^T = U_2V_2^TU_1U_1^T = U_2V_2^T \in \partial\|L_0X^+\|_*,$$

which gives that L_0X^+ is an optimal solution to the convex optimization problem in (11).

It remains to prove that the optimal solution to (11) is unique. We shall consider a feasible perturbation $A = L_0X^+ + \Delta$ and show that the objective strictly increases whenever $\Delta \neq 0$. We have

$$0 = \mathcal{P}_\Omega(AX - L_0) = \mathcal{P}_\Omega(L_0X^+X - L_0 + \Delta X),$$

which gives that

$$\mathcal{P}_\Omega(\Delta X) = 0, \text{ i.e., } \Delta X \in \mathcal{P}_\Omega^\perp.$$

We also have $\Delta X \in \mathcal{P}_{V_1}$, and thus $\Delta X \in \mathcal{P}_{V_1} \cap \mathcal{P}_\Omega^\perp$. However, by Lemma 6.6 and Lemma 6.3, $\mathcal{P}_{V_1} \cap \mathcal{P}_\Omega^\perp = \{0\}$. As a consequence,

$$\Delta X = 0, \text{ i.e., } \Delta^T \in U_1^\perp \subseteq V_2^\perp,$$

where $U_1^\perp \subseteq V_2^\perp$ follows from $V_2 \subseteq U_1$. Then we have

$$\begin{aligned} \|L_0X^+ + \Delta\|_* &= \left\| \begin{bmatrix} U_2^T \\ (U_2^\perp)^T \end{bmatrix} (L_0X^+ + \Delta)[V_2, V_2^\perp] \right\|_* \\ &= \left\| \begin{bmatrix} U_2^T L_0X^+ V_2 & U_2^T \Delta V_2^\perp \\ 0 & (U_2^\perp)^T \Delta V_2^\perp \end{bmatrix} \right\|_*. \end{aligned}$$

By Lemma 6.4,

$$\|L_0X^+ + \Delta\|_* \geq \|U_2^T L_0X^+ V_2\|_* = \|L_0X^+\|_*,$$

where the equality can hold if and only if

$$U_2^T \Delta V_2^\perp = 0 \text{ and } (U_2^\perp)^T \Delta V_2^\perp = 0.$$

This gives that $\Delta V_2^\perp = 0$, i.e., $\Delta^T \in V_2$. However, we have already proven that $\Delta^T \in V_2^\perp$. Thus, $\|L_0X^+ + \Delta\|_*$ is strictly greater than $\|L_0X^+\|_*$ unless $\Delta = 0$. In other words, $A_0 = L_0X^+$ is the unique minimizer to (11). \square

6.3 Proof to Theorem 3.2

Proof. Let the SVD of L_0 be $U_0 \Sigma_0 V_0^T$. Denote $\mathcal{P}_{U_0}(\cdot) = U_0 U_0^T(\cdot)$, $\mathcal{P}_{V_0}(\cdot) = (\cdot) V_0 V_0^T$ and $\mathcal{P}_{T_0}(\cdot) = \mathcal{P}_{U_0}(\cdot) + \mathcal{P}_{V_0}(\cdot) - \mathcal{P}_{U_0} \mathcal{P}_{V_0}(\cdot)$. Suppose that L_0 is incoherent, $\text{rank}(L_0) \leq \delta n_2 / (c \log n_1)$ and Ω is a 2D index set sampled using a Bernoulli model,

$$\Pr((i, j) \in \Omega) = \rho_0 > \delta.$$

Under these conditions, Theorem 4.1 of [4] has proven that

$$\|\mathcal{P}_{T_0} \mathcal{P}_{\Omega}^{\perp} \mathcal{P}_{T_0}\| < 1 - \rho_0 + \delta < 1$$

holds with high probability. Note that

$$\begin{aligned} \mathcal{P}_{U_0} \mathcal{P}_{T_0}(M) &= \mathcal{P}_{U_0}(\mathcal{P}_{U_0}(M) + \mathcal{P}_{V_0}(M) - \mathcal{P}_{U_0} \mathcal{P}_{V_0}(M)) \\ &= \mathcal{P}_{U_0}(M) \end{aligned}$$

and

$$\begin{aligned} \mathcal{P}_{T_0} \mathcal{P}_{U_0}(M) &= \mathcal{P}_{U_0} \mathcal{P}_{U_0}(M) + \mathcal{P}_{V_0} \mathcal{P}_{U_0}(M) - \mathcal{P}_{U_0} \mathcal{P}_{V_0} \mathcal{P}_{U_0}(M) \\ &= \mathcal{P}_{U_0}(M). \end{aligned}$$

Hence,

$$\begin{aligned} \|\mathcal{P}_{U_0} \mathcal{P}_{\Omega}^{\perp} \mathcal{P}_{U_0}\| &= \|\mathcal{P}_{U_0} \mathcal{P}_{T_0} \mathcal{P}_{\Omega}^{\perp} \mathcal{P}_{T_0} \mathcal{P}_{U_0}\| \\ &\leq \|\mathcal{P}_{T_0} \mathcal{P}_{\Omega}^{\perp} \mathcal{P}_{T_0}\| < 1. \end{aligned}$$

By Lemma 6.6, U_0 is Ω -isometric. Then it follows from Lemma 3.1 that L_0 is Ω -isometric. Similarly, it could be proved that L_0^T is Ω^T -isometric with high probability. \square

6.4 Proof to Theorem 3.3

Proof. By $y_0 \in \mathcal{S}_0 \subseteq \text{span}\{A\}$, $y_0 = AA^+ y_0$. By $y_0 = [y_b; y_u]$ and $A = [A_b; A_u]$,

$$y_b = A_b A^+ y_0.$$

That is, $x_0 = A^+ y_0$ is a feasible solution to the problem in (6). Provided that $y_b \in \mathbb{R}^k$ and the dictionary matrix A is k -isomeric, Definition 3.1 gives that

$$\text{rank}(A_b) = \text{rank}(A),$$

which implies that the rows of A_b can linearly represent the rows of A , i.e.,

$$\text{span}\{A_b^T\} = \text{span}\{A^T\}.$$

Since $A^+ y_0 \in \text{span}\{A^T\}$, it follows that there exists a dual vector $w \in \mathbb{R}^p$ obeying

$$A_b^T w = A^+ y_0, \text{ i.e., } A_b^T w \in \partial \frac{1}{2} \|A^+ y_0\|_2^2.$$

By standard convexity arguments [30], $x_0 = A^+ y_0$ is an optimal solution to (6). Since $\|\cdot\|_2^2$ is strongly convex, the optimal solution to (6) is unique. \square

6.5 Proof to Theorem 3.4

Proof. Denote the SVD of A as $U \Sigma V$. By $L_0 \in \text{span}\{A\}$, $AX_0 = AA^+ L_0 = UU^T L_0 = L_0$; that is, $X_0 = A^+ L_0$ is a feasible solution to (7). By Lemma 3.1 and Lemma 6.5, the operator $\mathcal{P}_U \mathcal{P}_{\Omega} \mathcal{P}_U$ is invertible. As a consequence, we could define a matrix W as

$$W = \mathcal{P}_U (\mathcal{P}_U \mathcal{P}_{\Omega} \mathcal{P}_U)^{-1} ((A^T)^+ X_0).$$

Then it can be calculated that

$$\begin{aligned} A^T \mathcal{P}_{\Omega}(W) &= A^T \mathcal{P}_U \mathcal{P}_{\Omega}(W) \\ &= A^T \mathcal{P}_U \mathcal{P}_{\Omega} \mathcal{P}_U (\mathcal{P}_U \mathcal{P}_{\Omega} \mathcal{P}_U)^{-1} ((A^T)^+ X_0) \\ &= A^T (A^T)^+ X_0 = V V^T X_0 \\ &= X_0 \in \partial \frac{1}{2} \|X_0\|_F^2, \end{aligned}$$

where $V V^T X_0 = X_0$ is concluded from the fact that $X_0 = A^+ L_0 \in \text{span}(A^T)$. Since $\|X\|_F^2$ is a strongly convex function of X , it follows from the standard convexity arguments [30] that $X_0 = A^+ L_0$ is the unique optimal solution to the problem in (7). \square

6.6 Proof to Theorem 3.5

Proof. Since $A_0 = U_0 \Sigma_0^{\frac{1}{2}} Q^T$ and $X_0 = Q \Sigma_0^{\frac{1}{2}} V_0^T$, we have the following: 1) $A_0 X_0 = L_0$; 2) $L_0 \in \text{span}\{A_0\}$ and A_0 is Ω -isomeric; 3) $L_0^T \in \text{span}\{X_0^T\}$ and X_0^T is Ω^T -isomeric. By Theorem 3.4,

$$X_0 = Q \Sigma_0^{\frac{1}{2}} V_0^T = A_0^+ L_0 = \arg \min_X \|X\|_F^2, \text{ s.t. } \mathcal{P}_\Omega(A_0 X - L_0) = 0,$$

$$A_0 = U_0 \Sigma_0^{\frac{1}{2}} Q^T = L_0 X_0^+ = \arg \min_A \|A\|_F^2, \text{ s.t. } \mathcal{P}_\Omega(A X_0 - L_0) = 0.$$

Hence, (A_0, X_0) is a critical point to the problem in (8). \square

6.7 Proof to Theorem 3.6

Proof. Since $A_0 = U_0 \Sigma_0^{\frac{2}{3}} Q^T$ and $X_0 = Q \Sigma_0^{\frac{1}{3}} V_0^T$, we have the following: 1) $A_0 X_0 = L_0$; 2) $L_0 \in \text{span}\{A_0\}$ and A_0 is Ω -isomeric; 3) $L_0^T \in \text{span}\{X_0^T\}$ and X_0^T is Ω^T -isomeric. By Theorem 3.4,

$$\begin{aligned} X_0 &= Q \Sigma_0^{\frac{1}{3}} V_0^T = A_0^+ L_0 \\ &= \arg \min_X \frac{1}{2} \|X\|_F^2, \text{ s.t. } \mathcal{P}_\Omega(A_0 X - L_0) = 0. \end{aligned}$$

By Lemma 6.9,

$$\begin{aligned} A_0 &= U_0 \Sigma_0^{\frac{2}{3}} Q^T = L_0 X_0^+ \\ &= \arg \min_A \|A\|_*, \text{ s.t. } \mathcal{P}_\Omega(A X_0 - L_0) = 0. \end{aligned}$$

Hence, (A_0, X_0) is a critical point to the problem in (9). \square